Date 18 August 2016
Your reference WOZ150011
Our reference ECN-WIND-2016-112

Contact
T +31 224 56 4086
verhoef@ecn.nl

P.O. Box 1, 1755 ZG Petten, The Netherlands
Netherlands Enterprise Agency (RVO.nl)
Croeselaan 15
3521 BJ UTRECHT
THE NETHERLANDS

Subject Supply of Meteorological and Oceanographic data for Borssele Wind Farm Zone Period 16 June – 18 July 2016 (Lot1)

Dear Sir/Madam,

The following two Meteorological and Oceanographic data reports produced by Fugro OCEANOR AS for Lot1 measurement campaign have been reviewed by ECN Wind Energy:

1. Supply of Meteorological and Oceanographic data at Borssele Wind Farm Zone (BWFZ)
   Monthly Progress Report : 16 June – 18 July 2016.
   Reference No: C75339_MPR09_R0
2. Supply of Meteorological and Oceanographic data at Borssele Wind Farm Zone (BWFZ)
   Validation report : 16 June – 18 July 2016.
   Reference No: C75339_VAL09_R1

ECN has found that the above referenced reports provide a sufficient detail for potential users of the provided data to perform analysis.

Please note that the provided dataset (Period 9 , Version 2 dd. 20160817) can be retrieved via the website : www.WindOpZee.net. It should also be noted that in the documents it is mentioned that additional Water Level Sensor data will become available after retrieving the sensor. This data is at the present moment not available via the website and is also not part of this review. Additional actions need to be taken after the data becomes available.

.

Yours sincerely,

i.o. H. Verhoef

Hans Verhoef
Project Leader Measurements

Petten
Postbus 1
1755 ZG Petten

Westerduinweg 3
1755 LE Petten
The Netherlands

T +31 88 5 154 949
F +31 88 5 154 480
www.ecn.nl

VAT NL001752625B01
Trade register 41151233

THE NETHERLANDS ENTERPRISE AGENCY (RVO)

Supply of Meteorological and Oceanographic data at Borssele Wind Farm Zone (BWFZ)
Monthly Progress Report: 16 June - 18 July 2016

Reference No: C75339_MPR09_R0
26 July 2016

Fugro OCEANOR AS
Pirsenteret, P.O. Box 1224, Sluppen, N-7462 Trondheim, Norway
Tel: +47 73545200 Fax: +47 73525033, e-mail: trondheim@oceanor.com

Supply of Meteorological and Oceanographic data at Borssele Wind Farm Zone (BWFZ): C75339_MPR09_R0				
Rev	**Date**	**Originator**	**Checked & Approved**	**Issue Purpose**
0	26.07.2016	Lasse Lønseth	Olaf Sveggen	Final report.

Rev 0 – 26 July 2016	Originator	Checked & Approved
Signed:	Lasse Lønseth	Olaf Sveggen

This report is not to be used for contractual or engineering purposes unless the above is signed where indicated by both the originator of the report and the checker/approver and the report is designated 'FINAL'.

TABLE OF CONTENT

SUMMARY 1

1. INTRODUCTION 2

2. Instrumentation and measurement configuration 2

3. Summary of activities 6
   - 3.1 Buoy operation 6
   - 3.2 Health, Safety and Environment 6

4. Results 7
   - 4.1 Summary of results and data return 7
   - 4.2 Presentation of the received data 7
     - 4.2.1 Meteorological data 7
     - 4.2.2 Wave data 10
     - 4.2.3 Wind profile data 13
     - 4.2.4 Current velocity profile data 25
     - 4.2.5 Water level and bottom temperature data 32

Appendix A: Buoy deployment record

SUMMARY

The Seawatch Wind Lidar buoy is deployed at the Borssele Wind Farm Zone (BWFZ). This monthly report summarizes the activities during the period 16 June – 18 July 2016, and presents time series plots of the data collected during this period.

The buoy was first deployed on 11 June 2015 at 15:55 UTC, and a bottom mounted tide gauge (WLR) was deployed at 16:15 UTC on the same day. The buoy transmitted data continuously until transmissions stopped on 11 September, and it was recovered on 6 October 2015. The buoy was then repaired, and re-deployed on 12 November 2015. The Lidar stopped working on 26 December 2015 due to a technical problem, while the buoy continued measuring and transmitting data from all other sensors. The buoy was recovered for repair on 19 January 2016.

The spare Seawatch Wind Lidar buoy was deployed at the same position in the BWFZ on 12 February 2016 and is currently in operation.

1. INTRODUCTION

The Seawatch Wind Lidar buoy with serial no. WS149 was first deployed at the Borssele Wind Farm Zone (BWFZ) in the Dutch sector of the North Sea on 11 June 2015 at 15:55 with the bottom mooring weight at position 51° 42.41388' N, 3° 2.07708' E. The water depth at this location is approximately 30 m. A bottom mounted water level recorder (WLR) was deployed near the buoy at position 51° 42.4362' N, 3° 02.1030' E at the same time, transmitting data to the buoy in real time data via an acoustic link. Unfortunately the acoustic link broke down on 8th July 2015 so water level data are no longer received in real time, but the data are stored in the WLR for download when it is recovered.

Following the stop in the transmissions from the buoy on 11 September 2015 at 16:00, the buoy was recovered to shore on 6 October 2015 for inspection and repair. It was redeployed after repair on 12 November 2015 at 14:00. The multicat type workboat Multrasalvor 3 was used for this operation. A spare WLR with internal data storage only was deployed on 18th December 2015 to ensure water level data recovery.

The Lidar on Buoy WS149 stopped working on 26 December 2015 due to a technical problem with its power switch. After a long period of unworkable weather conditions, and some delay due to vessel unavailability, the buoy was recovered for repair on 19 January 2016. The buoy was replaced by the spare buoy WS157 which was deployed on 12 February 2016 at 13:00. This buoy has since collected good data, and this report presents the data collected from 16 June 2016 at 22:50 until 18 July 2016 at 10:20. Due to a number of minor gaps in the time series, it took 31.486 days to collect 30.5 days of good wind profile data.

The time reference used in this report is UTC.

2. Instrumentation and measurement configuration

The buoy is a Seawatch Wind Lidar Buoy based on the original Seawatch Wavescan buoy design with the following sensors:

- Wavesense: 3-directional wave sensor
- Xsens 3-axes motion sensor
- Gill Windsonic M acoustic wind sensor
- Vaisala PTB330A air pressure sensor
- Vaisala HMP155 air temperature and humidity sensor
- Nortek Aquadopp 600kHz current profiler.
- ZephIR 300S Lidar.

An independent self-recording Aanderaa SeaGuard WLR tide gauge is located on the bottom. The WLR transmits data to the buoy via an acoustic link.

The buoy with mooring as deployed is presented in Figure 2.1, including the mooring for the WLR.

The measurement setup is detailed in Table 2-1. Details of sensor types and serial number can be found in Appendix A.

Table 2-1 Configuration of measurements by the Seawatch Wind Lidar buoy at Borssele Wind Farm Zone (BWFZ).

Instrument type	Sensor height (m)	Parameter measured	Sample height[2)] (m)	Sampling interval (s)	Averaging period (s)	Burst interval (s)	Trans-mitted?
Wavesense 3	0	Heave, pitch, roll, heading	0	0.5	Time series duration: 1024 s	600	No
		Sea state parameters (1)	0	600	1024	600	Yes
Xsens		Heave,east,north acceleration, q0,q1,q2,q3 (attitude quaternion)	0	0.5	N/A	3600	No
Gill Windsonic M	4.1	Wind speed, wind direction	4.1	1	600	600	Yes
Vaisala PTB330A	0.5	Air pressure	0.5	30	60	600	Yes
Vaisala HMP155	4.1	Air temperature Air humidity	4.1	5	60	600	Yes
Nortek Aquadopp	-1	Current speed and direction profile, water temperature (at 1 m depth)	-4 -6 … -30 (14 levels)	N/A	600	600	Yes
ZephIR 300S Lidar	2	Wind speed and direction at 10 heights (The 11th level, the so called reference level which is not configurable, is also located at 40 m and referred to as 40.0 Ref.)	30.0 40.0 40.0 ref 60.0 80.0 100.0 120.0 140.0 160.0 180.0 200.0	≈ 17.4 s[1)]	600	600	Yes
Aanderaa WLR (SeaGuard) via acoustic link	-30	Water pressure Temperature	-30	600	60	600	Yes[3)]

1) This is the approximate time between the beginning of one sweep of the profile and the next one, the interval may vary slightly. The ZephIR sweeps one level at a time beginning at the lowest one, and after the top level has been swept it uses some time for calculations and re-focusing back to the lowest level for a new sweep.
2) Height relative to actual sea surface. The depth of the WLR is an approximate number.
3) The WLR data are not transmitted after 8 July 2015 due to failure of the acoustic link. An additional self-contained WLR was deployed 18 December 2015 to ensure data recovery.

Table 2.2 Definitions of wave parameters presented in this report

H	Individual wave height
Hmax	= Max(H): Height of the highest individual wave in the sample, measured from crest to trough
m0, m1, m2, m4, m-1, m-2	Moments of the spectrum about the origin: $\int f^k S(f)df$ where $S(f)$ is the spectral density and the wave frequency, f, is in the range 0.04 - 0.50 Hz
Hm0	Estimate of significant wave height, Hs, $Hm0 = 4\sqrt{m0}$
Tp	Period of spectral peak = $1/f_p$, The frequency/period with the highest energy
Tm01	Estimate of the average wave period; $Tm01 = m0/m1$
Tm02	Another estimate of the average wave period; $Tm02 = \sqrt{\frac{m0}{m2}}$
ThTp	Mean wave direction at the spectral peak ("The direction of most energetic waves")
Mdir	Wave direction averaged over the whole spectrum
	Directions are given in degrees clockwise from north, giving the direction the waves come from. (0° from north, 90° from east, etc.)

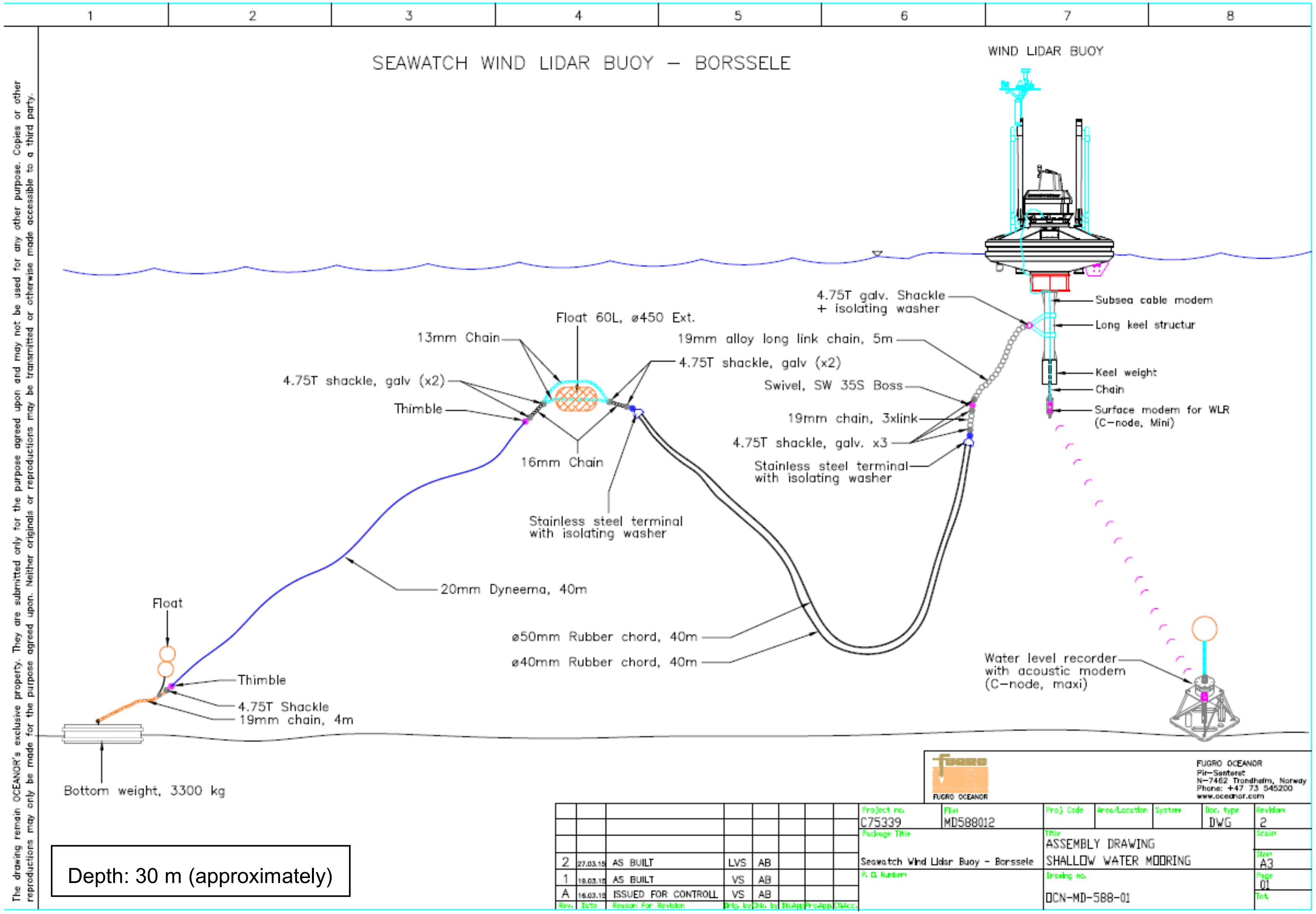

Figure 2.1 Mooring design for the Wind Lidar Buoy and Seaguard WLR bottom unit as deployed at Borssele Wind Farm Zone (BWFZ) 11 June 2015.

3. Summary of activities

3.1 Buoy operation

The Seawatch Wind Lidar buoy with serial no. WS149 and a bottom mounted Water Level Recorder (SeaGuard WLR) were deployed at the Borssele Wind Farm Zone in the Dutch sector of the North Sea on 11 June 2015. The buoy was deployed at 15:55 with the bottom mooring weight at position 51° 42.41388' N, 3° 2.07708' E. A bottom mounted WLR was deployed at position 51° 42.4362' N, 3° 02.1030' E. The WLR transmitted data to the buoy in real time data via an acoustic link[1]. The sounder depth was recorded as approximately 30 m.

After approximately 3 months of continuous good operation the transmissions from the buoy ended on 11 September 2015 at 15:50. Therefore the buoy had to be recovered to shore for diagnosis and repair. The recovery was achieved on 6 October 2015 at 11:30 by the multicat type workboat Multrasalvor 3, while the WLR unit remained on the bottom.

The buoy was redeployed by the Multrasalvor 3 on 12 November 2015 at 14:00, and good data were received from 14:20. To ensure recovery of water level data a new WLR without acoustic communication was deployed on 18 December 2015 together with the buoy. The Lidar on buoy WS149 stopped working on 26 December 2015, and after a long period of mainly unworkable weather conditions, and some delay due to vessel unavailability, the buoy was recovered for repair on 19 January 2016. The buoy was replaced by the spare buoy WS157 which was deployed at exactly the same position on 12 February 2016 at 13:00. These operations were carried out using the Multrasalvor 3.

Good data were received from 12 February 2016 at 13:20. This reporting period covers the fifth month of operation after the deployment of WS157, which extends from 16 June 2016 at 22:50 until 18 July 2016 at 10:20, and contains 30.5 days of wind profile data.

3.2 Health, Safety and Environment

There were no incidents, near misses or accidents in connection with the recovery operation on 19 January and the deployment operation on 12 February 2016. There has been no operational activity in the project during the present reporting month.

[1] The acoustic link failed and the transmissions of water pressure data from the WLR stopped on 8th July 2015. It is expected that the internal recording of data in the WLR will continue undisturbed until it is recovered.

4. Results

4.1 Summary of results and data return

The buoy transmitted data continuously from all sensors from 16 June 2016 at 22:50 until 18 July 2016 at 10:20, with the exception of some minor gaps. There are a few short gaps in the Lidar data where the received data are replaced by the "missing data" flag at all heights. The gaps are mainly short dropouts where 1-2 records are missing in the Lidar data only. The longer gaps in the Lidar data lasted from 00:00 to 01:00 on 21 June, from 16:00 to 19:00 on 3 July, and the longest outage occurred on 16 July from 09:00 to 09:30, and from 10:00-14:20. During the latter data gap the data are missing from all sensors on the buoy, and it appears that the data collection restarts to run normally after an automatic restart of the buoy system. Due to the gaps it took 31.486 days to collect 30.5 days of good wind profile data[2].

The number of hours of good data compared to the total obtainable hours of data is presented in Table 4-1.

Table 4-1 Data return during the period 16 June 2016 at 22:50 – 18 July 2016 at 10:20.

Measurement device	Length of data period (days)	Length of data set (days)	Average availability (%)
Lidar wind profile sensor	31.486	30.500	96.87
Wave sensor	31.486	30.951	98.24
Current velocity and direction sensor	31.486	31.139	98.83
Atmospheric pressure sensor	31.486	31.153	98.88
Air temperature sensor	31.486	21.875	69.43
Water Level Sensor *	31.486	0.000	0.00

* The real time transmitted water level data are unexpectedly lost due to breakdown of the acoustic link. However, the complete data series will be recovered when the instrument is recovered.

4.2 Presentation of the received data

The following presentations show good data transmitted from the buoy via Iridium satellite during the period 16 June 2016 at 22:50 – 18 July 2016 at 10:20.

4.2.1 Meteorological data

The following plots present the air pressure, air temperature, and sea surface temperature.

The air temperature and humidity sensor failed on 16 July 2016 at 08:20, from that time the sensor did not return any new measurements. Earlier in this period this sensor frequently failed to update the values of temperature and humidity for a few 10-minute periods at a time, causing short gaps in the data series.

[2] Additional gaps in the real time transmitted Turbulence Intensity (TI) data are caused by breaks in the satellite dial-up transmission link. The data that were not received in real time are stored internally in the buoy and will be downloaded from the buoy when it is recovered.

The water temperature sensor is part of the current profiler, the AquaDopp, and data recovery for water temperature is the same as for current profile data.

Figure 4.1 Time series plots of air pressure (upper panel), air and water temperature (lower panel), 16 - 27 Jun 2016.

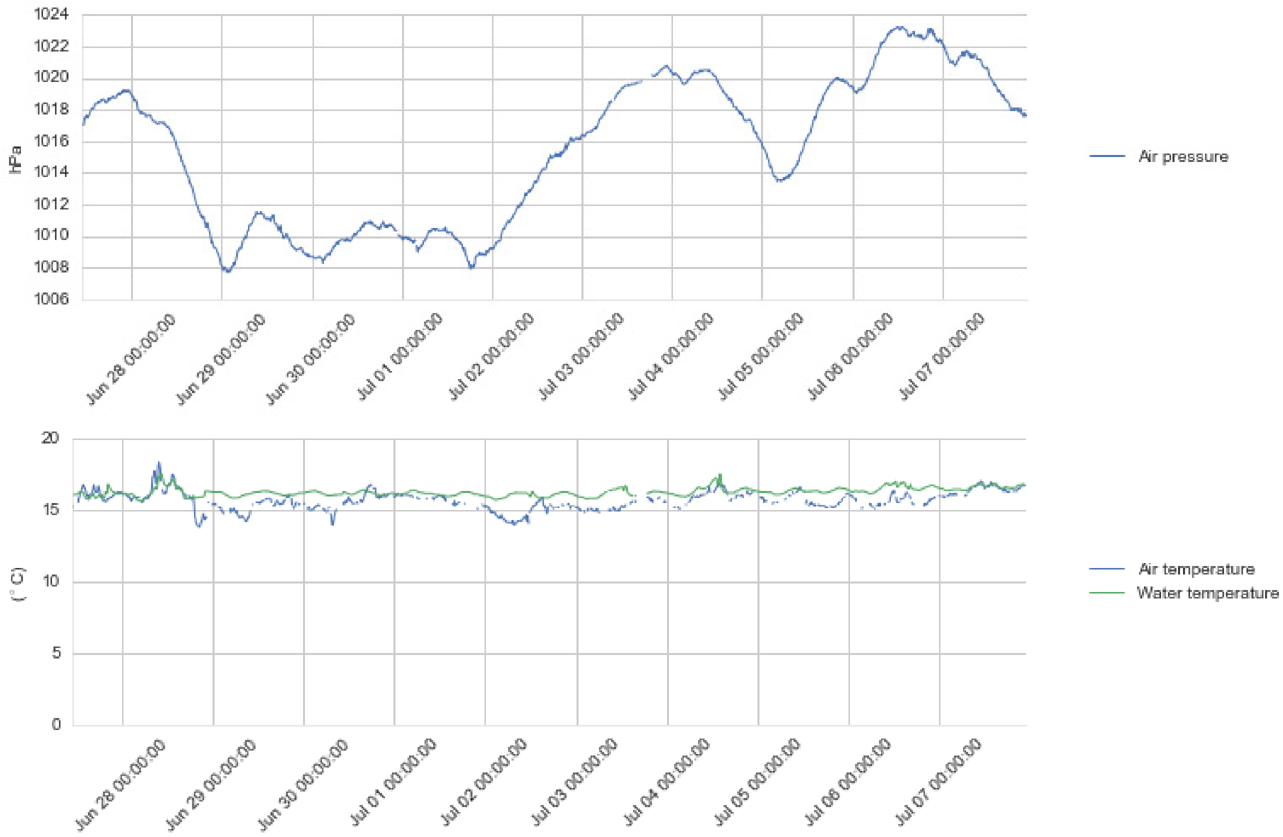

Figure 4.2 Time series plots of air pressure (upper panel), air and water temperature (lower panel), 27 Jun – 7 Jul 2016.

Figure 4.3 Time series plots of air pressure (upper panel), air and water temperature (lower panel), 7 - 18 Jul 2016.

4.2.2 Wave data

The next plots present wave height, period and direction. The wave sensor has generally functioned well. However, there are gaps in the wave data, and all other data, on 21 June, 3 July and 16 July 2016.

The highest significant wave height (Hm0) measured in this period was 2.87 m from a south-westerly direction (~230°) on 11 July at 14:30. Wind speeds of 13-19 m/s from south-southwest (~210°) were observed in the profile prior to the highest sea states. The highest single wave with a height of 4.57 m was observed on 1 July at 22:20.

The variations in wave height agree well with the wind speeds in general. The average wave period parameters Tm01 and Tm02 show semidiurnal variations which can be explained by the shift in frequency when the waves are travelling along with or opposing the current direction, since the tidal current direction varies in a semi-diurnal pattern.

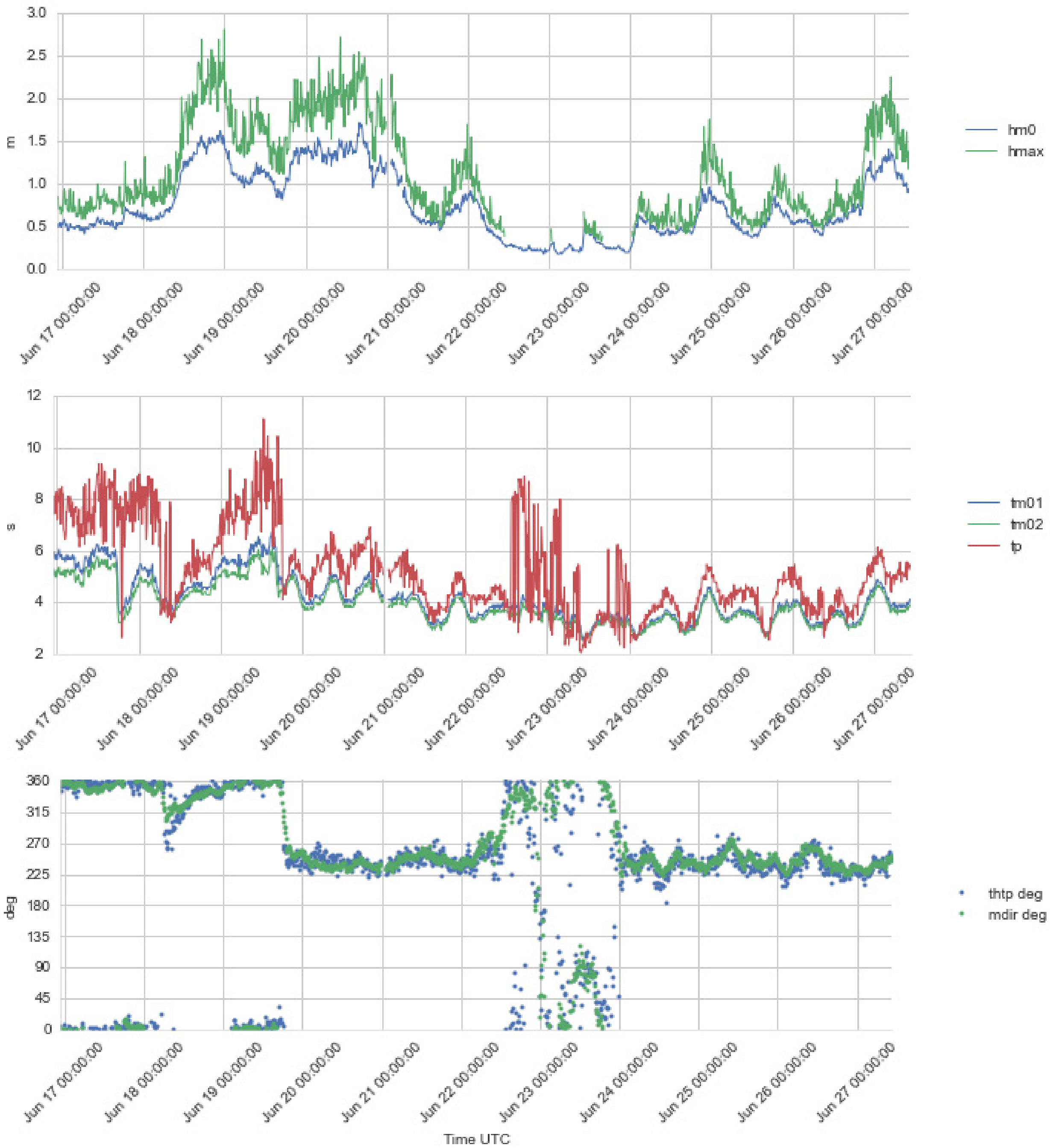

Figure 4.4 Time series plots of wave height (Hm0 and Hmax) (upper panel), wave period (Tm01, Tm02 and Tp) (second panel), and wave direction (ThTp and Mdir) (lower panel), 16 - 27 Jun 2016.

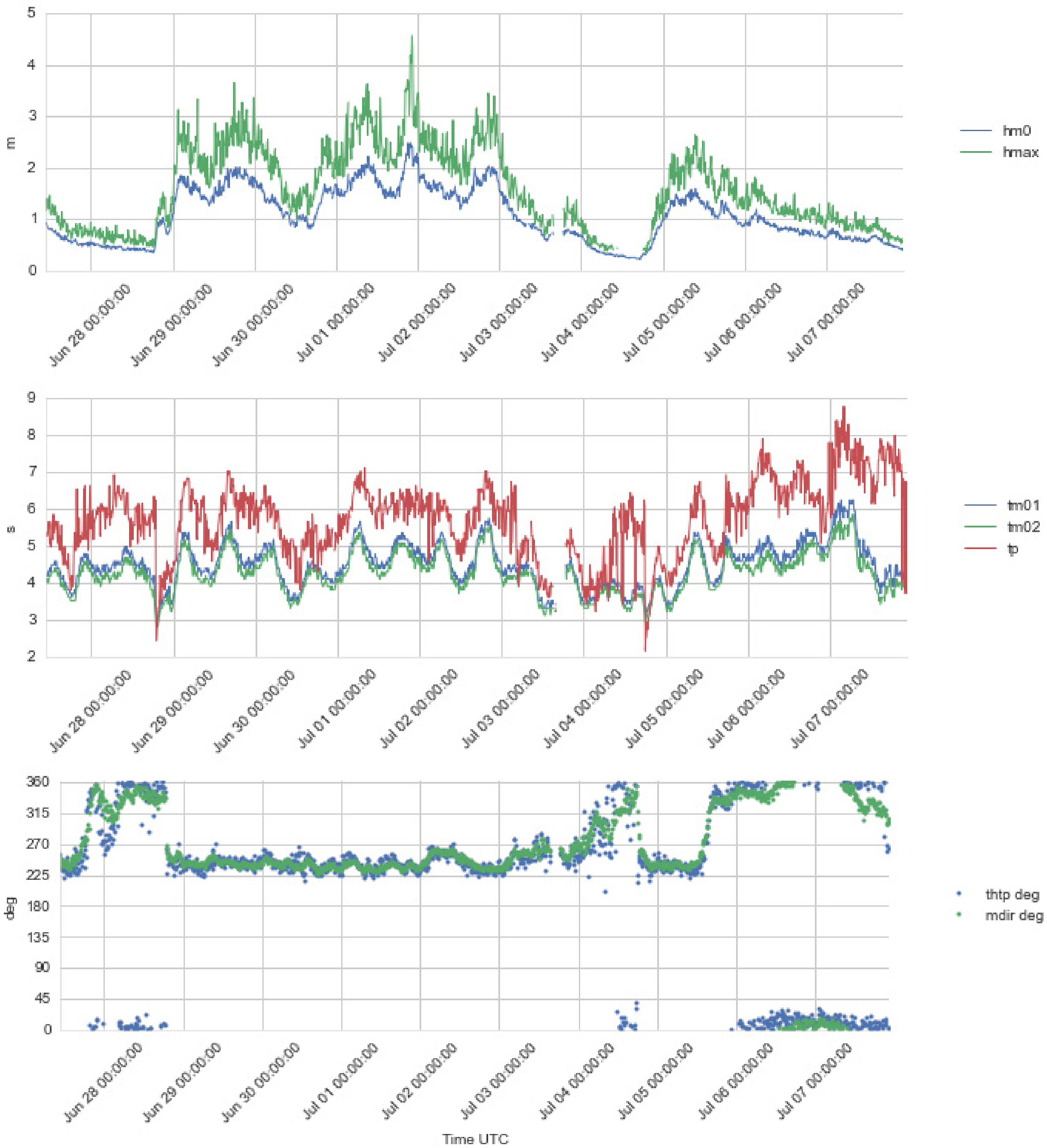

Figure 4.5 Time series plots of wave height (Hm0 and Hmax) (upper panel), wave period (Tm01, Tm02 and Tp) (second panel), and wave direction (ThTp and Mdir) (lower panel), 27 Jun – 7 Jul 2016.

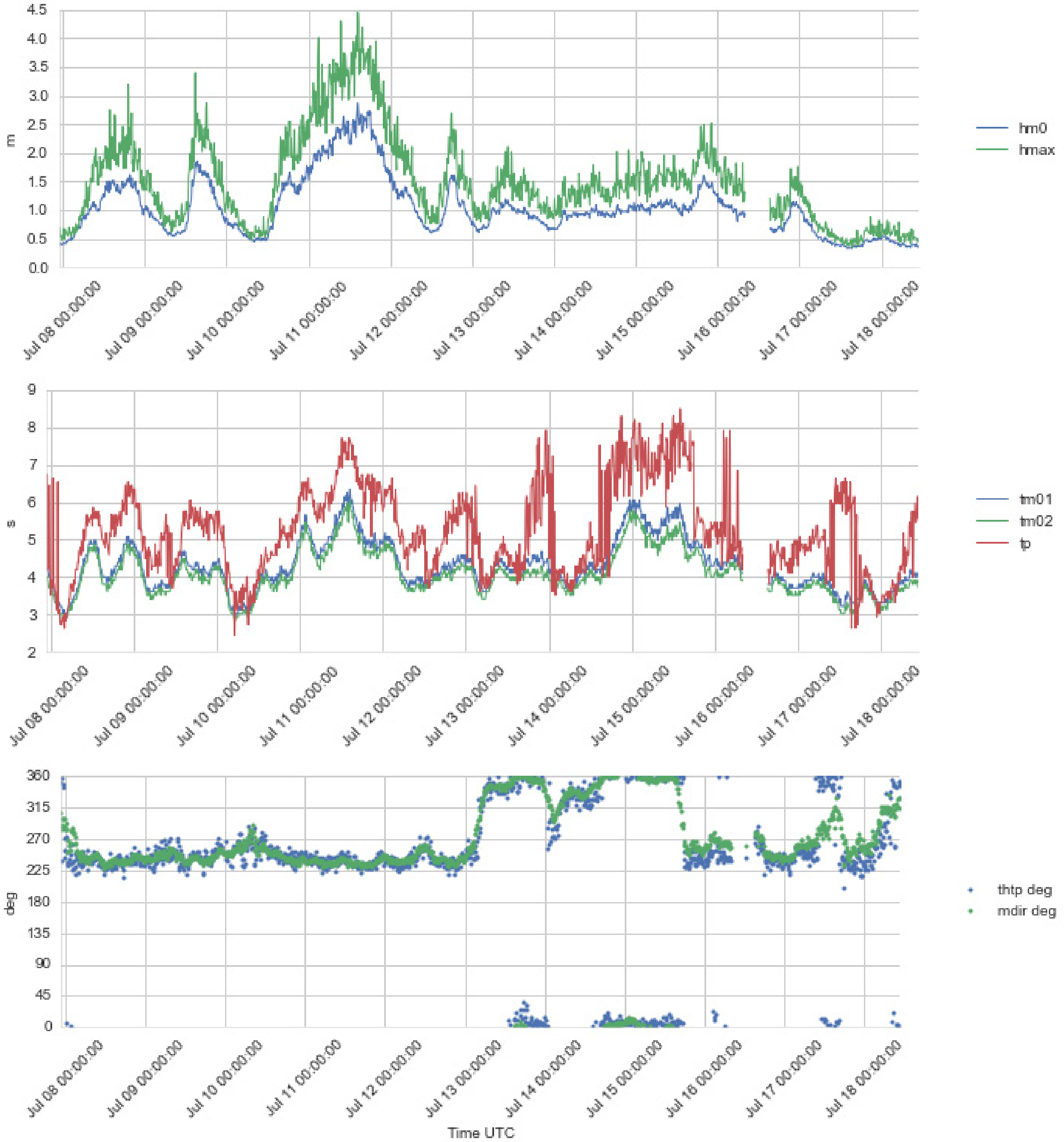

Figure 4.6 Time series plots of wave height (Hm0 and Hmax) (upper panel), wave period (Tm01, Tm02 and Tp) (second panel), and wave direction (ThTp and Mdir) (lower panel), 7 - 18 Jul 2016.

4.2.3 Wind profile data

In the wind and wave direction plots 0° and 360° indicate direction from the north.

The following plots show the wind speed and direction data from the Gill wind sensor mounted at 4 m height on the buoy mast. The data from the Gill sensor are generally good. In this period 10 min mean wind speeds up to 14.7 m/s and gusts up to 20.4 m/s were measured at 4 m above the sea surface on 26 April 2016. The average wind speed at this height was 6.5 m/s.

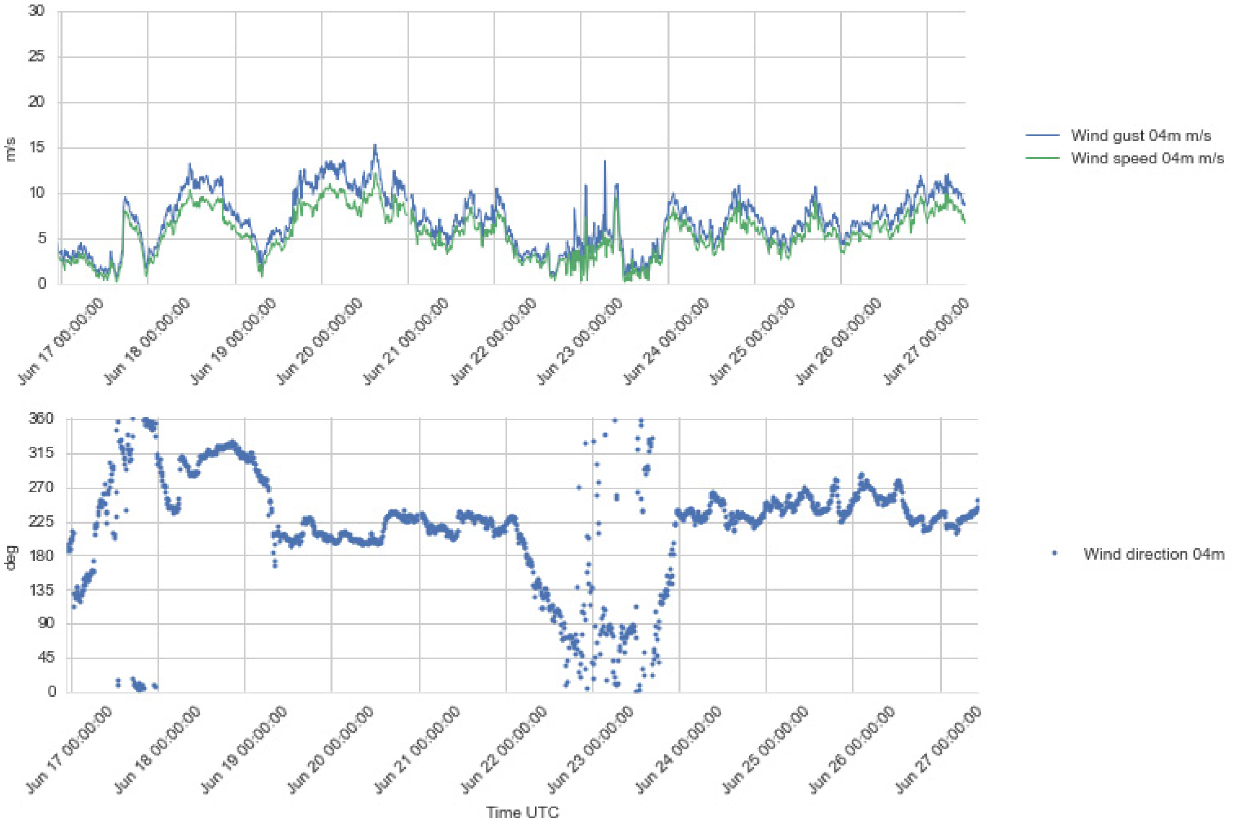

Figure 4.7 Plots of wind speed and gust (upper), and wind direction (lower) at 4 m a.s.l., 16 - 27 Jun 2016.

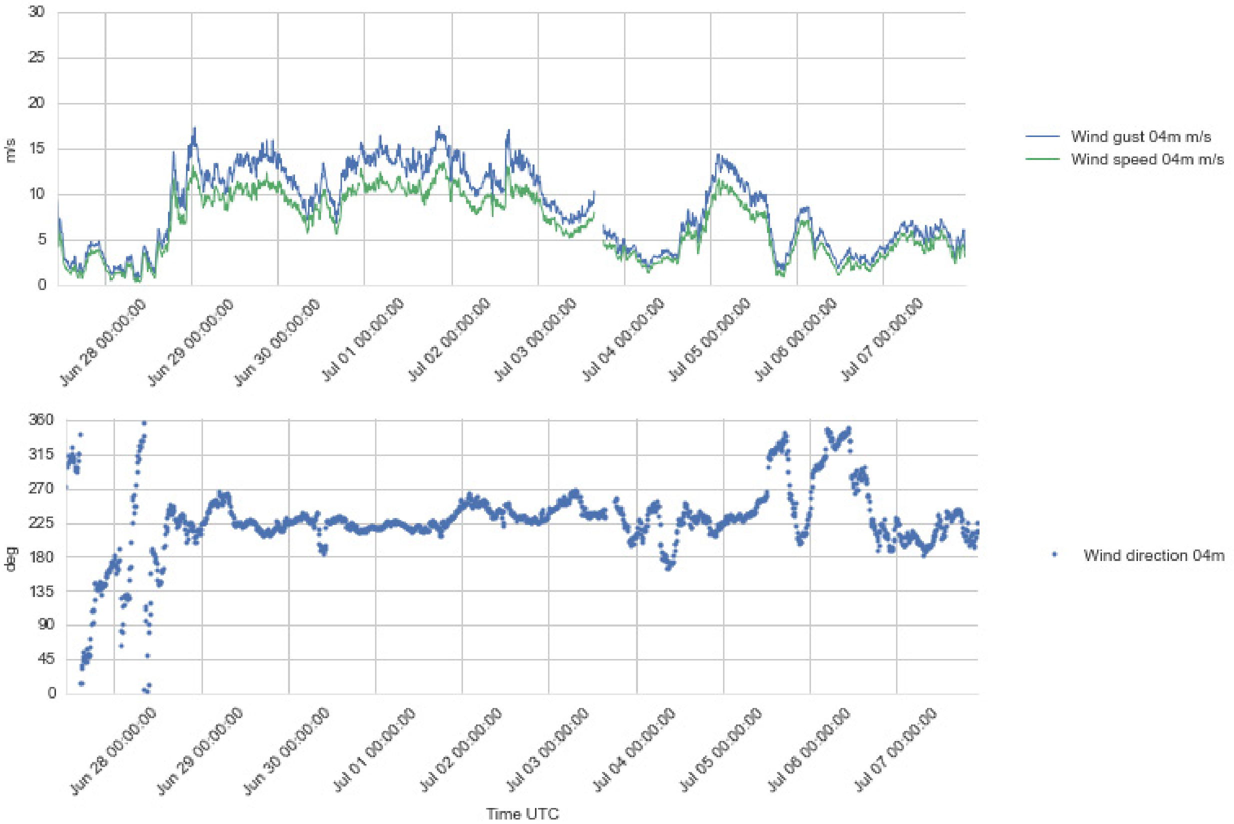

Figure 4.8 Plots of wind speed and gust (upper), and wind direction (lower) at 4 m a.s.l., 27 Jun – 7 Jul 2016.

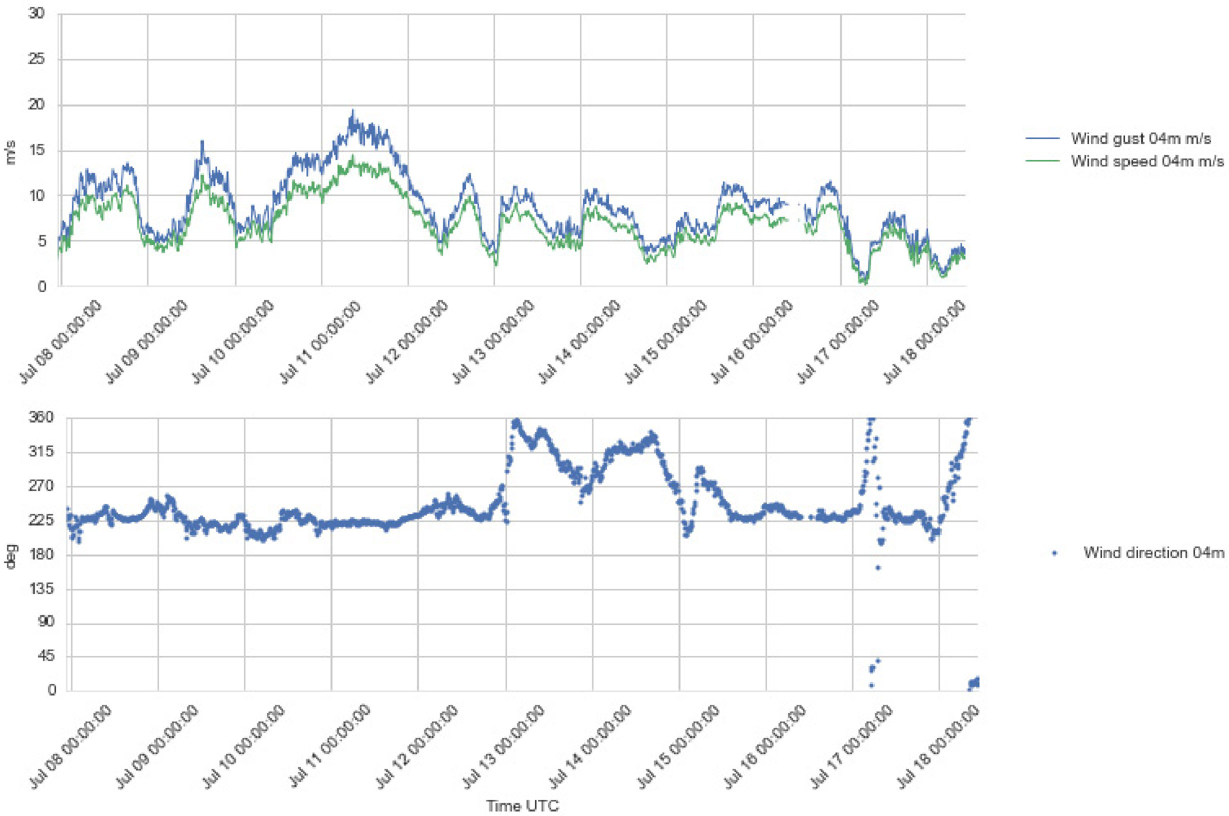

Figure 4.9 Plots of wind speed and gust (upper), and wind direction (lower) at 4 m a.s.l., 7 - 18 Jul 2016.

The wind profiling data from the Lidar are presented in the following plots showing the time series of 10 min. mean wind for each individual level. Plots of the derived parameters Inflow Angle and Turbulence Intensity[3] are also presented.

The Inflow Angle (IA) is the angle of the 3-dimensional wind vector based on the ten minute averaged values of the horizontal and vertical wind velocity components. IA can be positive or negative; a positive IA means that the wind vector has an upward directed vertical component. The Turbulence Intensity (TI) is defined as TI = $\sigma/\bar{u}$ where σ is the standard deviation and $\bar{u}$ is the mean of the wind speed for a 10-min period. Note that this definition frequently gives relatively high values in situations with low but variable wind speed. This is noticeable in the plots, as seen for example on 22 – 23 June, 28 June and 4 – 6 July 2016.

The highest observed horizontal mean wind speed during this month varies from 17.6 m/s at 30 m to 21.4 m/s at 200 m above the surface. The 30 m maximum was measured on 11 July 2016 at 09:00, while the wind speed at the 200 m level reached its maximum 30 minutes earlier, in an period with quite strong winds and relatively homogeneous wind conditions in the entire profile from 30 to 200 m height. The wind direction was in the SW sector (210-225°) in that period.

[3] Turbulence Intensity is transmitted using the Iridium Dial-up data transfer mode, separately from the horizontal wind speed, direction and inflow angle which are transmitted as short burst data messages. There are a few gaps in the TI data at times when the dial-up transfer failed, while the wind speed, direction and IA were received normally.

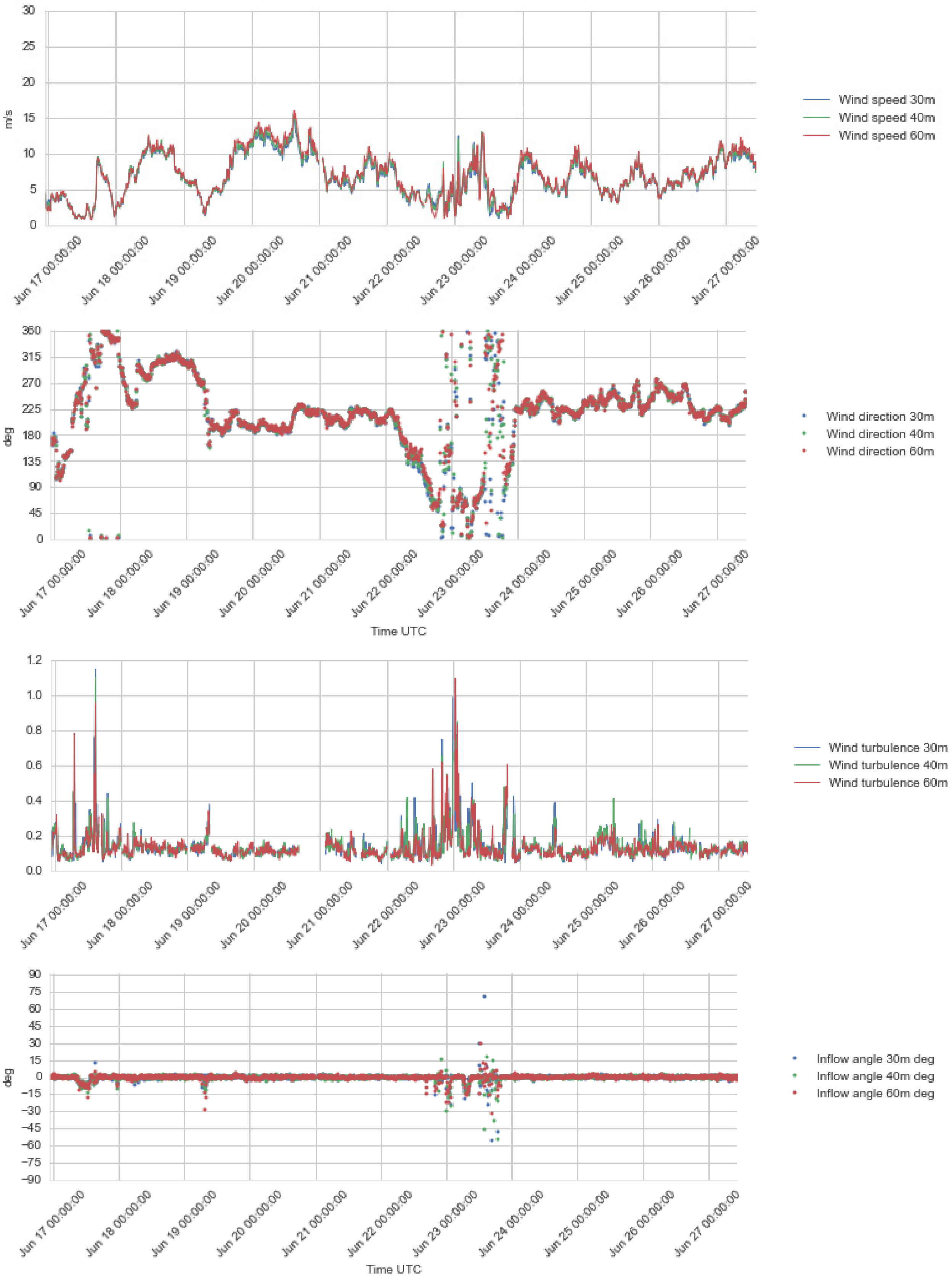

Figure 4.10 Plots of wind profile data, 30 – 60 m a.s.l., 16 – 27 Jun 2016.

From top to bottom: Wind speed, Wind direction, Turbulence Intensity, and Inflow Angle.

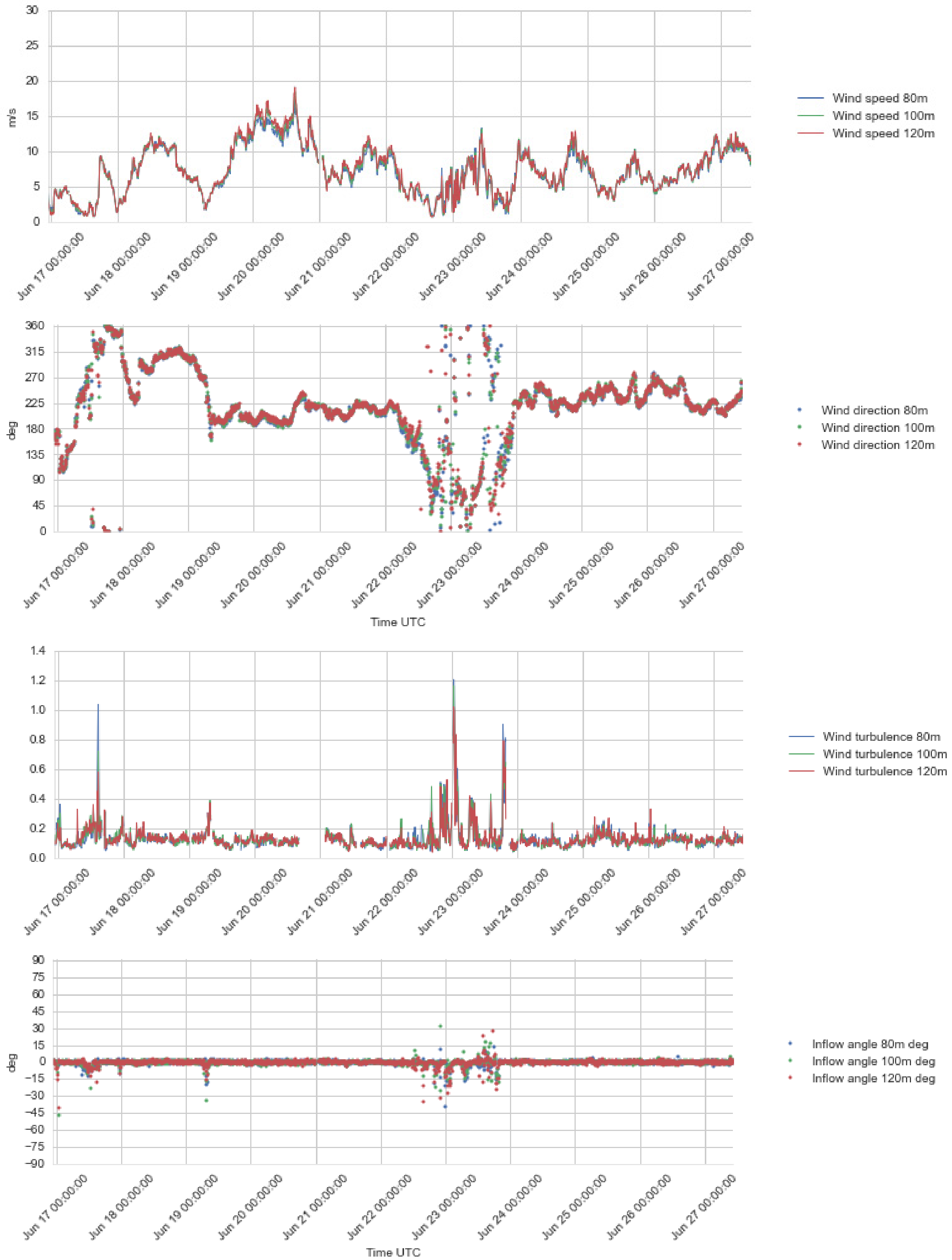

Figure 4.11 Plots of wind profile data, 80 – 120 m a.s.l., 16 – 27 Jun 2016.

From top to bottom: Wind speed, Wind direction, Turbulence Intensity, and Inflow Angle.

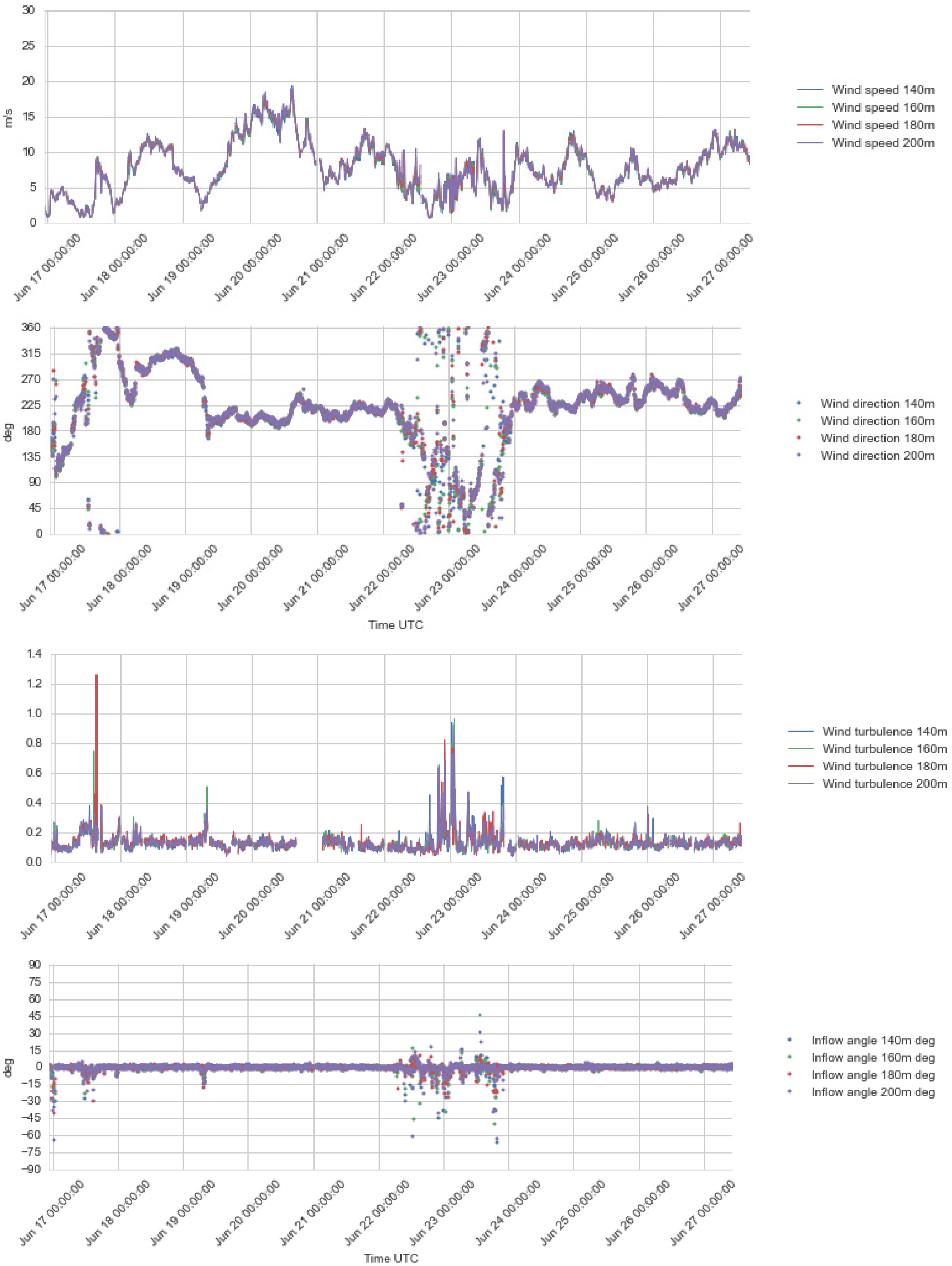

Figure 4.12 Plots of wind profile data, 140 – 200 m a.s.l., 16 – 27 Jun 2016.

From top to bottom: Wind speed, Wind direction, Turbulence Intensity, and Inflow Angle.

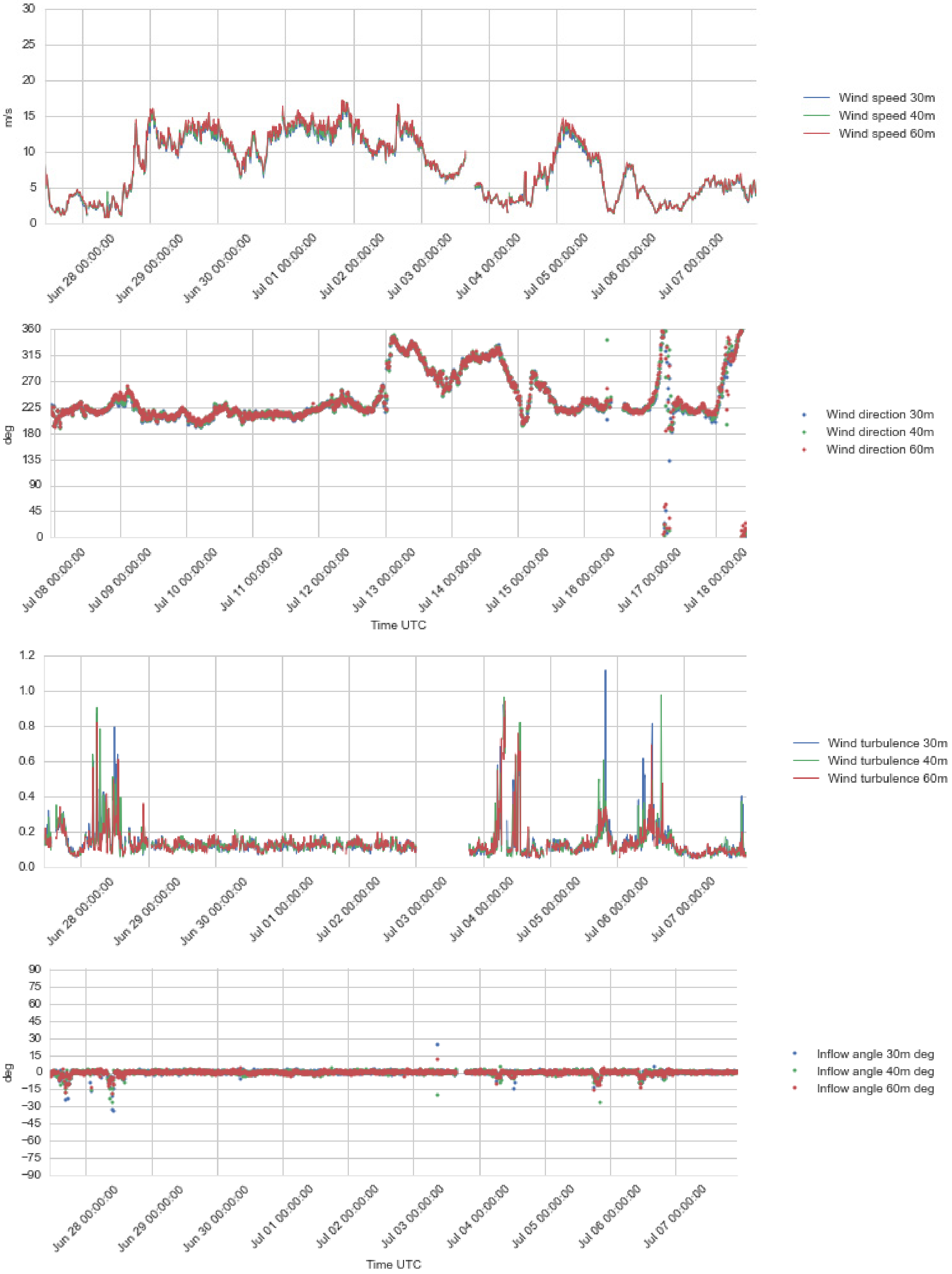

Figure 4.13 Plots of wind profile data, 30 – 60 m a.s.l., 27 Jun – 7 Jul 2016.

From top to bottom: Wind speed, Wind direction, Turbulence Intensity, and Inflow Angle.

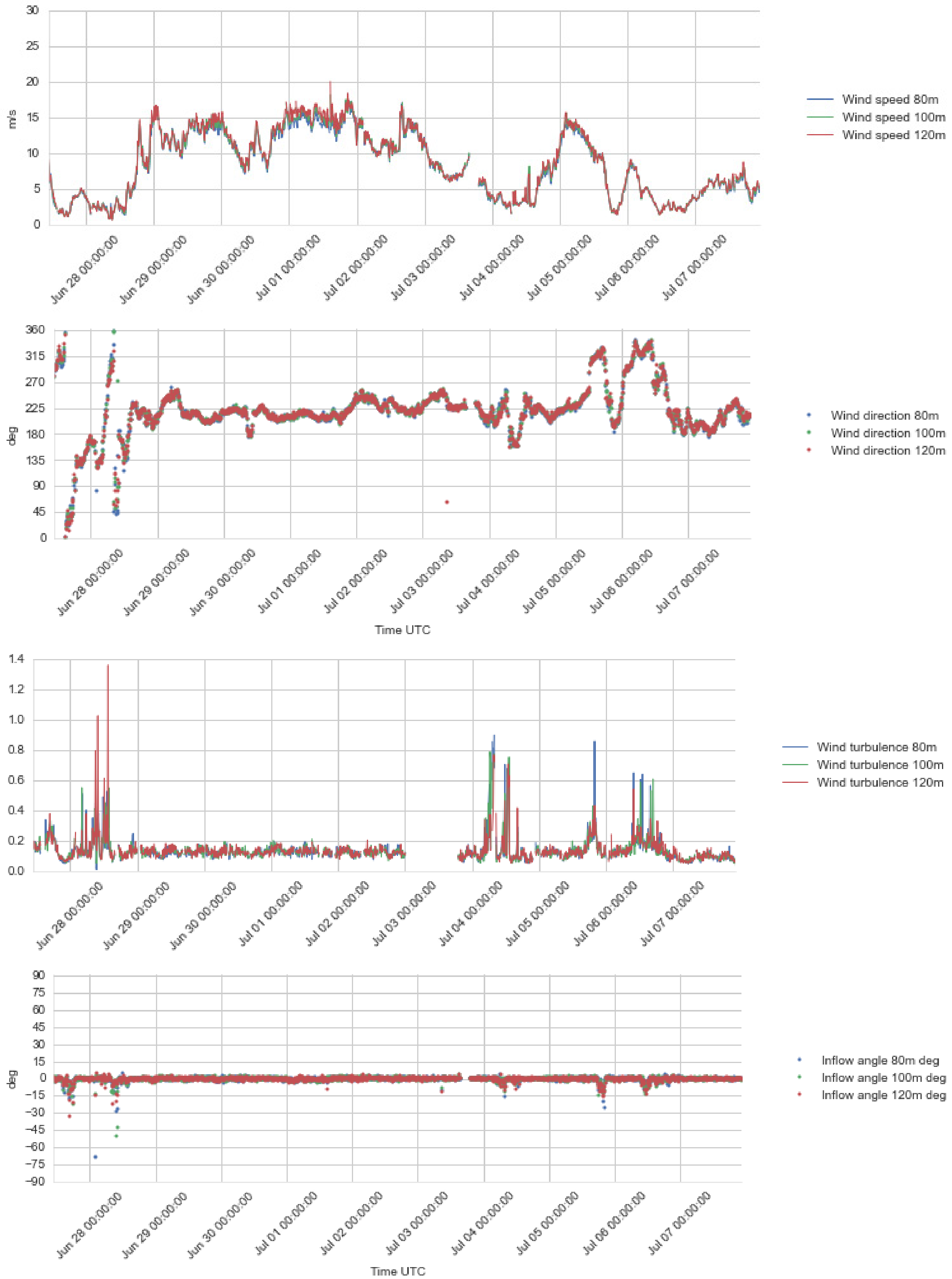

Figure 4.14 Plots of wind profile data, 80 – 120 m a.s.l., 27 Jun – 7 Jul 2016.

From top to bottom: Wind speed, Wind direction, Turbulence Intensity, and Inflow Angle.

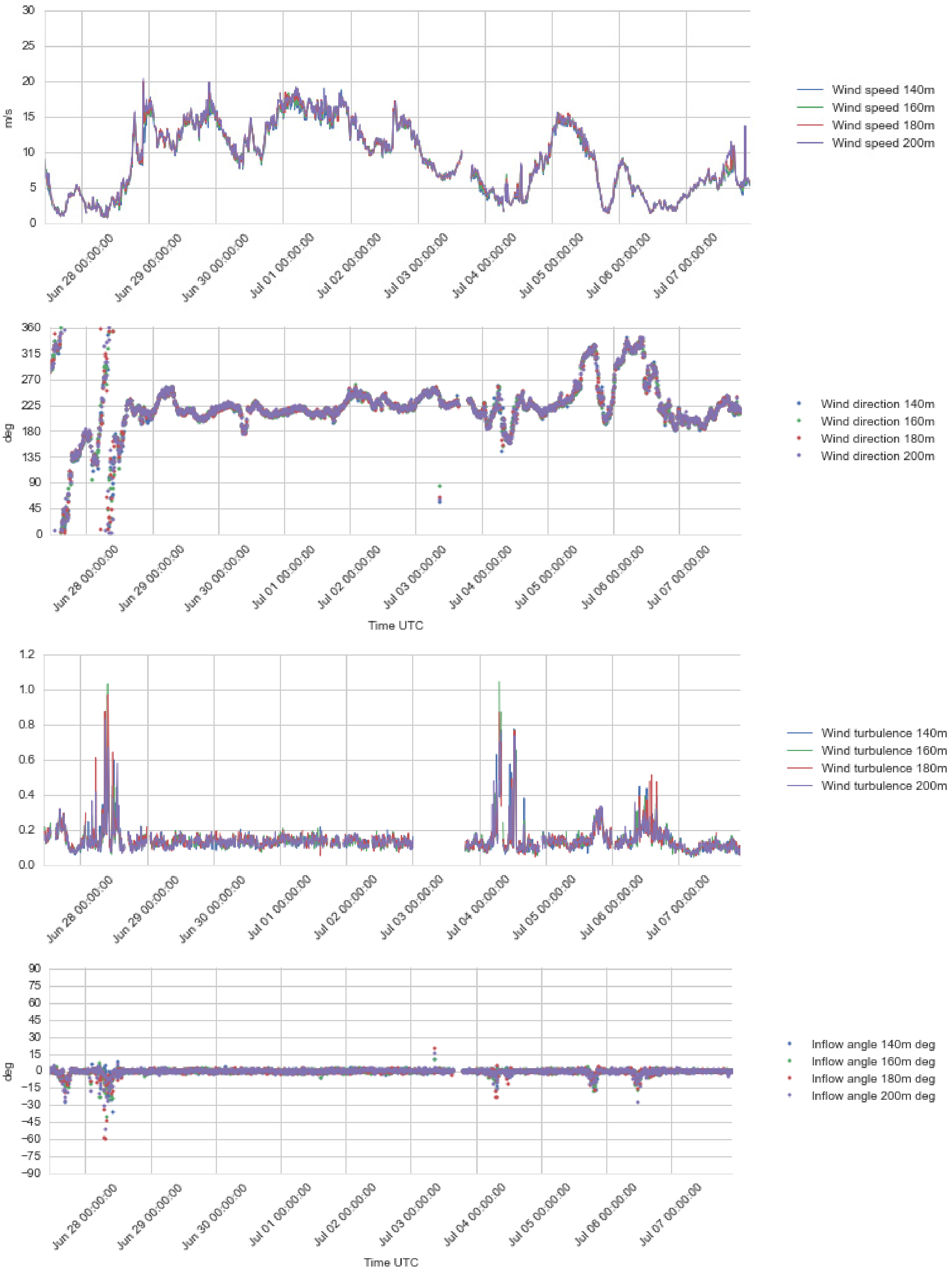

Figure 4.15 Plots of wind profile data, 140 – 200 m a.s.l., 27 Jun – 7 Jul 2016.

From top to bottom: Wind speed, Wind direction, Turbulence Intensity, and Inflow Angle.

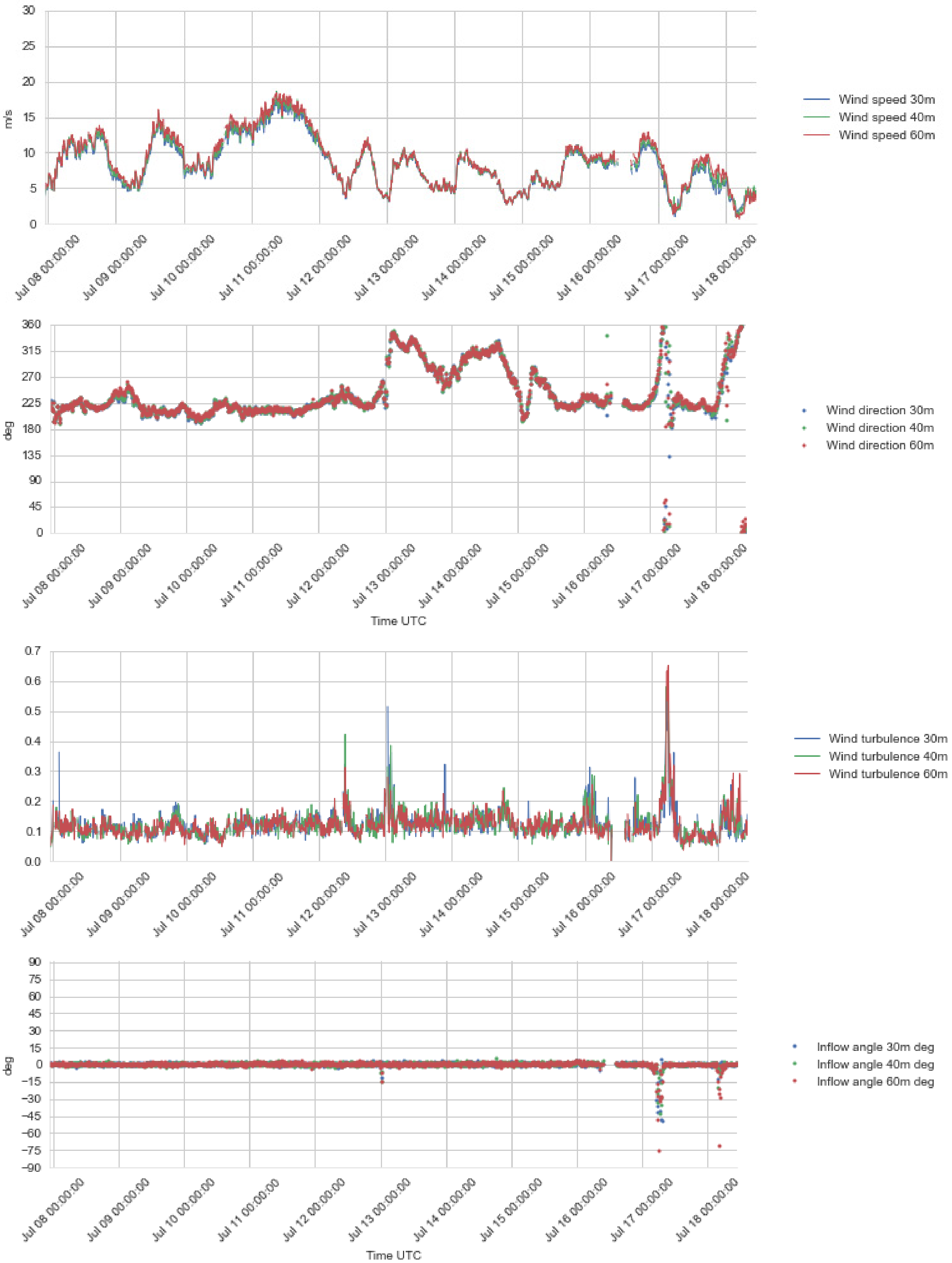

Figure 4.16 Plots of wind profile data, 30 – 60 m a.s.l., 7 - 18 Jul 2016.

From top to bottom: Wind speed, Wind direction, Turbulence Intensity, and Inflow Angle.

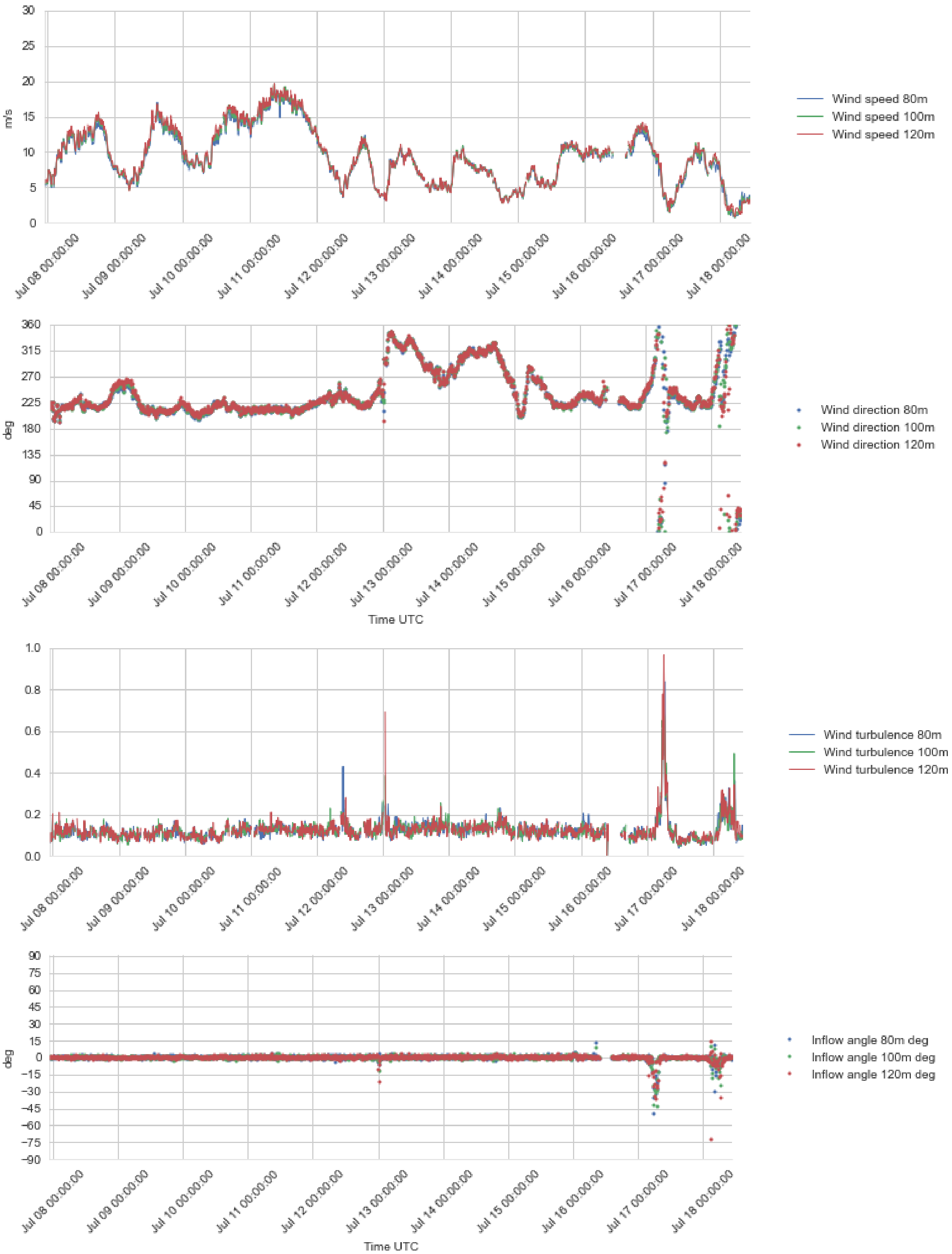

Figure 4.17 Plots of wind profile data, 80 – 120 m a.s.l., 7 - 18 Jul 2016.

From top to bottom: Wind speed, Wind direction, Turbulence Intensity, and Inflow Angle.

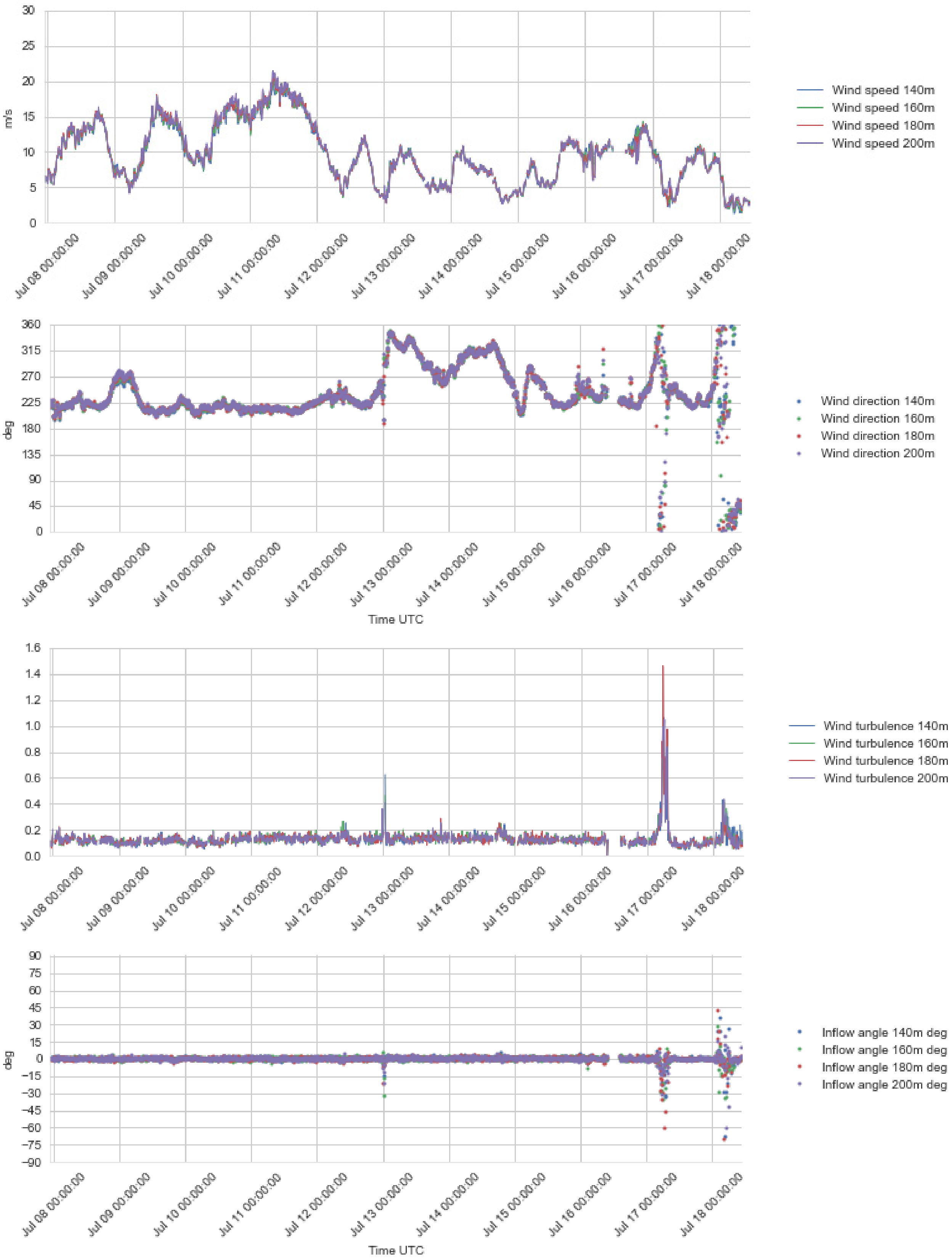

Figure 4.18 Plots of wind profile data, 140 – 200 m a.s.l., 7 - 18 Jul 2016.

From top to bottom: Wind speed, Wind direction, Turbulence Intensity, and Inflow Angle.

4.2.4 Current velocity profile data

The following plots show the current velocity profile time series. In these plots current direction 0° or 360° means that the current flows toward north, 90° indicates flow toward east etc. In general the current profiler has worked well, just a few data points were lost due to buoy restarting, but otherwise the series is continuous

As expected for this location the current velocity data show a very strong and consistent semi-diurnal tidal current pattern, completing two full rotations of the current vector per day, and four tidal current maxima; two toward south-southwest and two toward north-east. The quarter-diurnal peaks in the tidal current speed normally vary between 60 – 100 cm/s over the month, depending on the phases of the moon. However, we observe particularly strong surface current toward NNE on top of the tidal current during the period 21 – 28 June, with speeds in excess of 150 cm/s. This adds more than 50 cm/s to the normal tidal current.

The average current speed shows little variation in the profile above the bottom layer; from around 55 cm/s between 4 – 14 m below surface to 46 cm/s at 26 m depth. The maximum observed current speed was 154 cm/s toward North (7°) at 4 m depth.

At the lowest level, 30 m and, possibly, 28 m depth, the current speeds are reduced when the profiling beam hits the bottom. This usually occurs at every other peak in the current speed; that is when the strong current coincides with low tide.

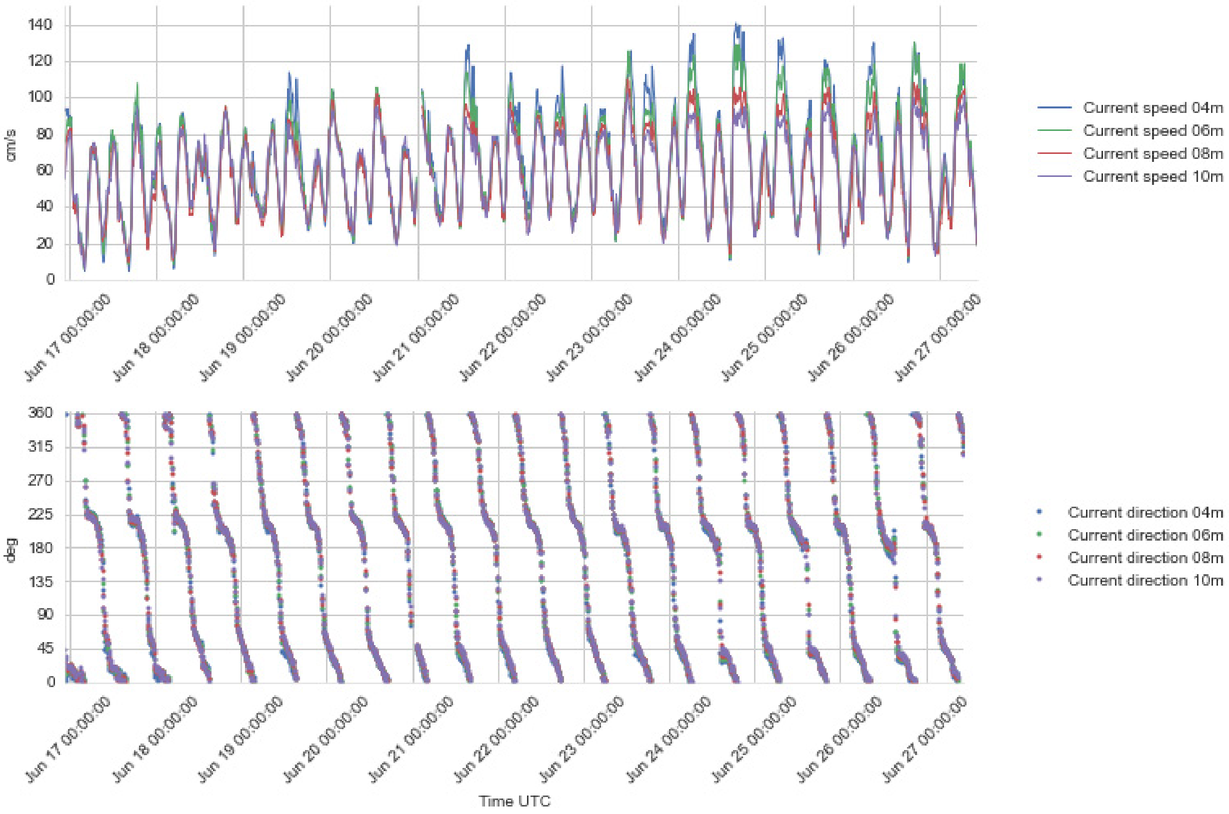

Figure 4.19 Time series plots of current speed (upper) and direction (lower panel), 4 - 10 m depth, 16 – 27 Jun 2016.

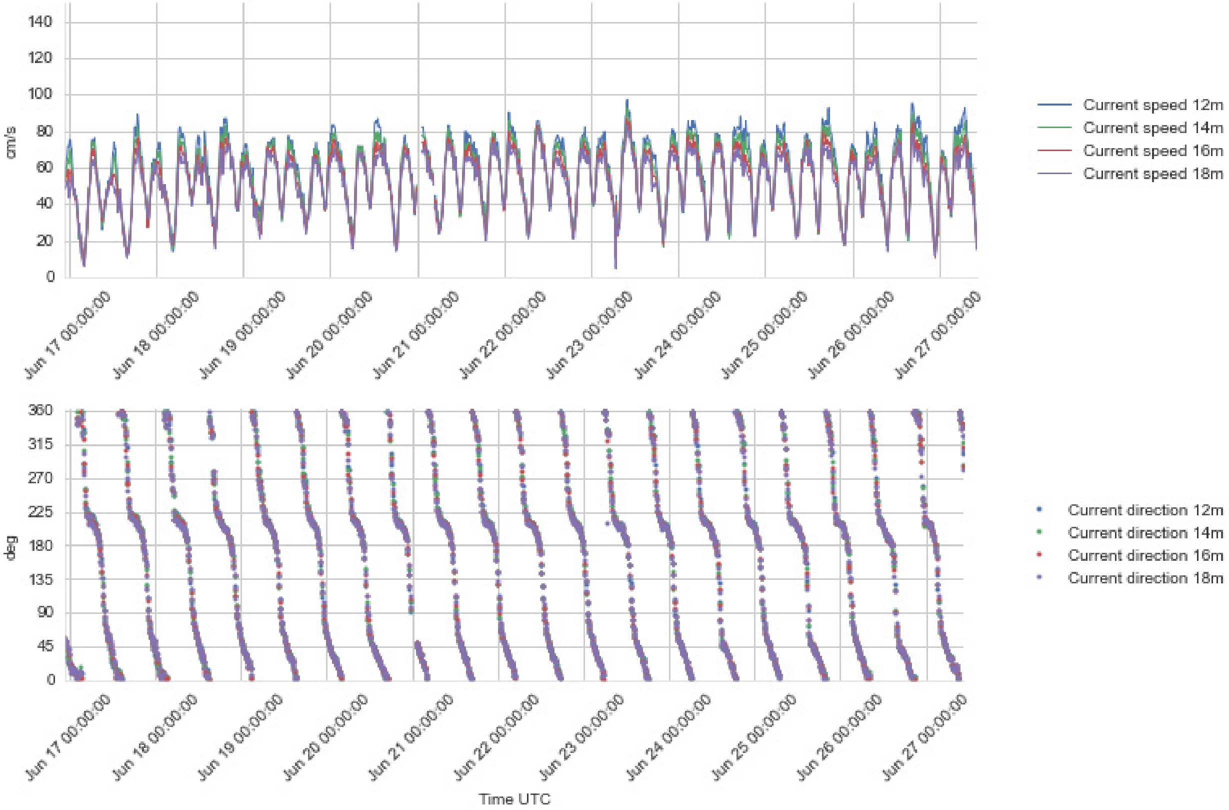

Figure 4.20 Time series plots of current speed (upper) and direction (lower panel), 12 - 18 m depth, 16 – 27 Jun 2016.

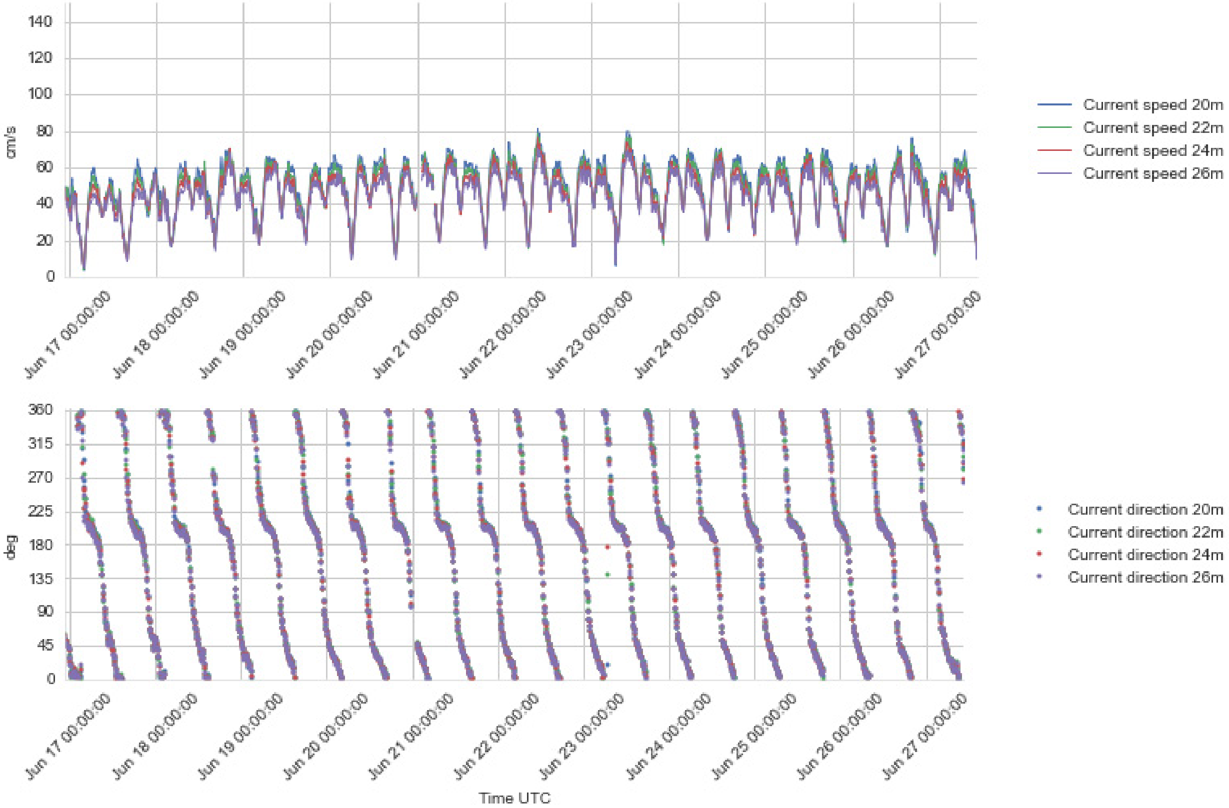

Figure 4.21 Time series plots of current speed (upper) and direction (lower panel), 20 - 26 m depth, 16 – 27 Jun 2016.

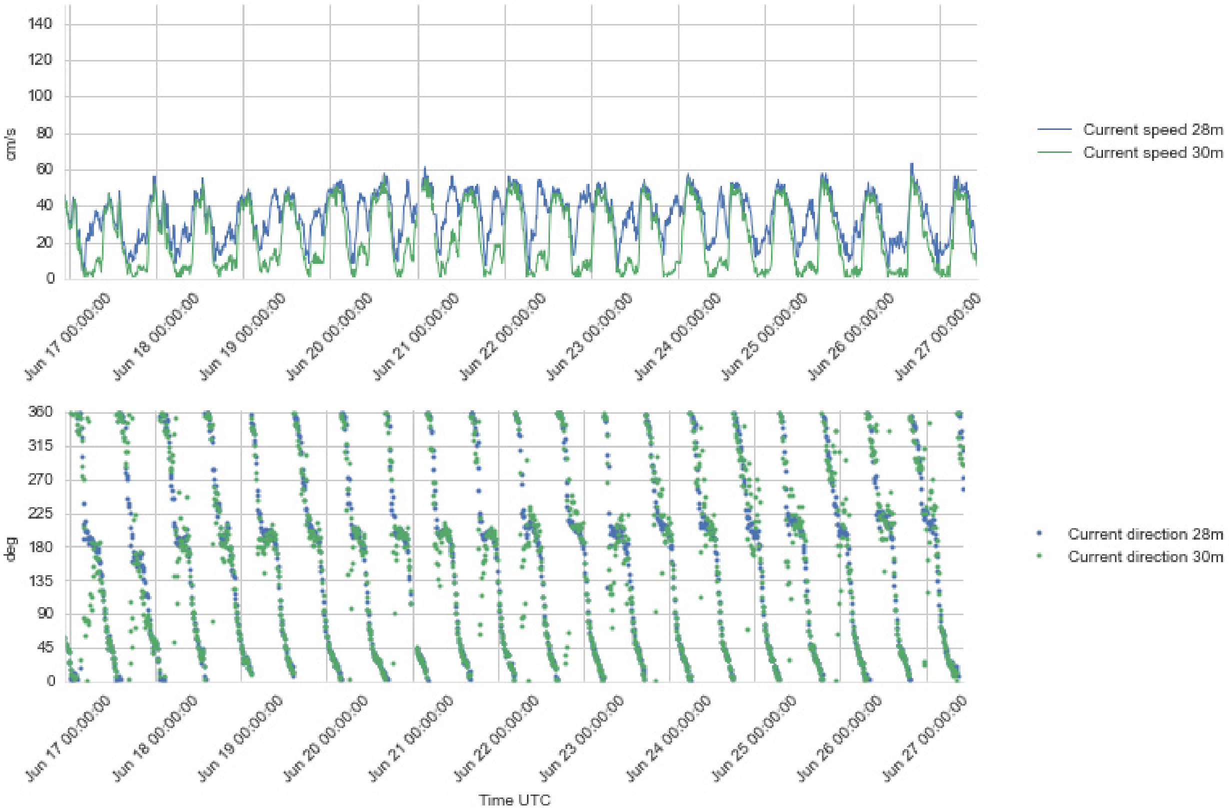

Figure 4.22 Time series plots of current speed (upper) and direction (lower panel), 28 - 30 m depth, 16 – 27 Jun 2016.

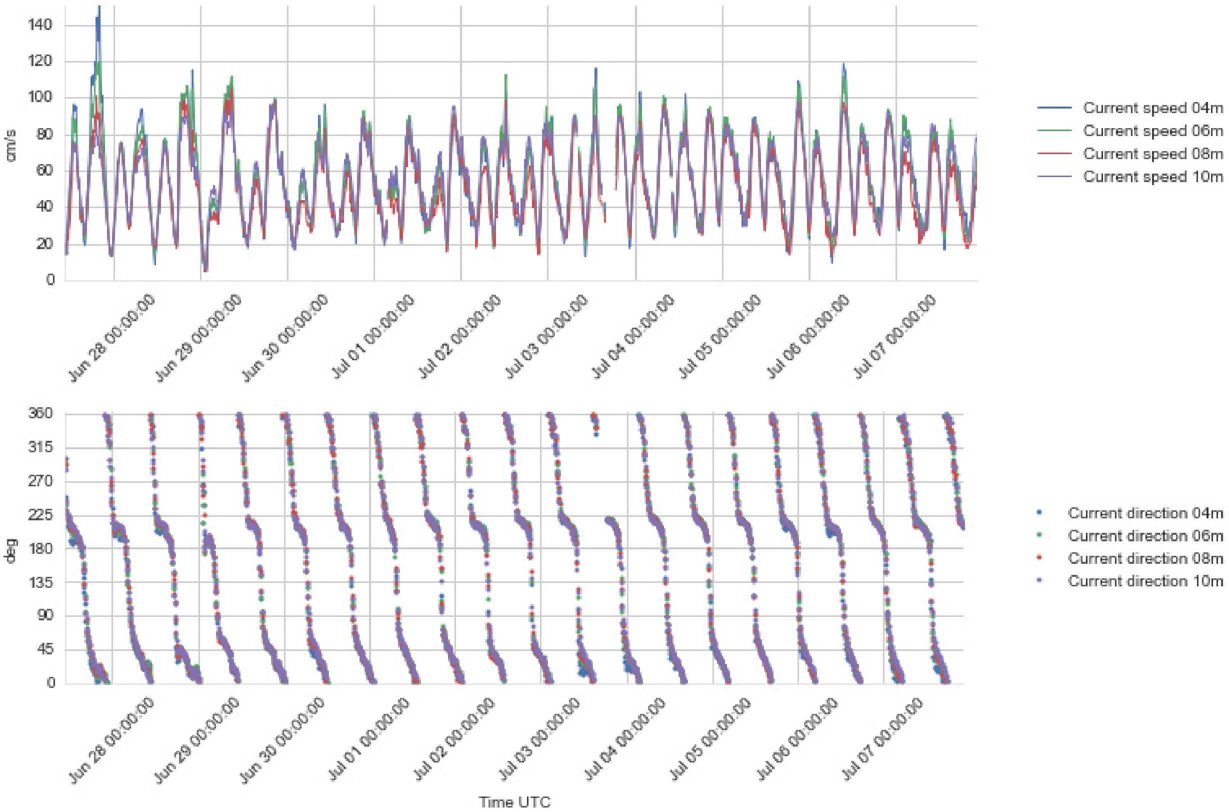

Figure 4.23 Time series plots of current speed (upper) and direction (lower panel), 4 - 10 m depth, 27 Jun – 7 Jul 2016.

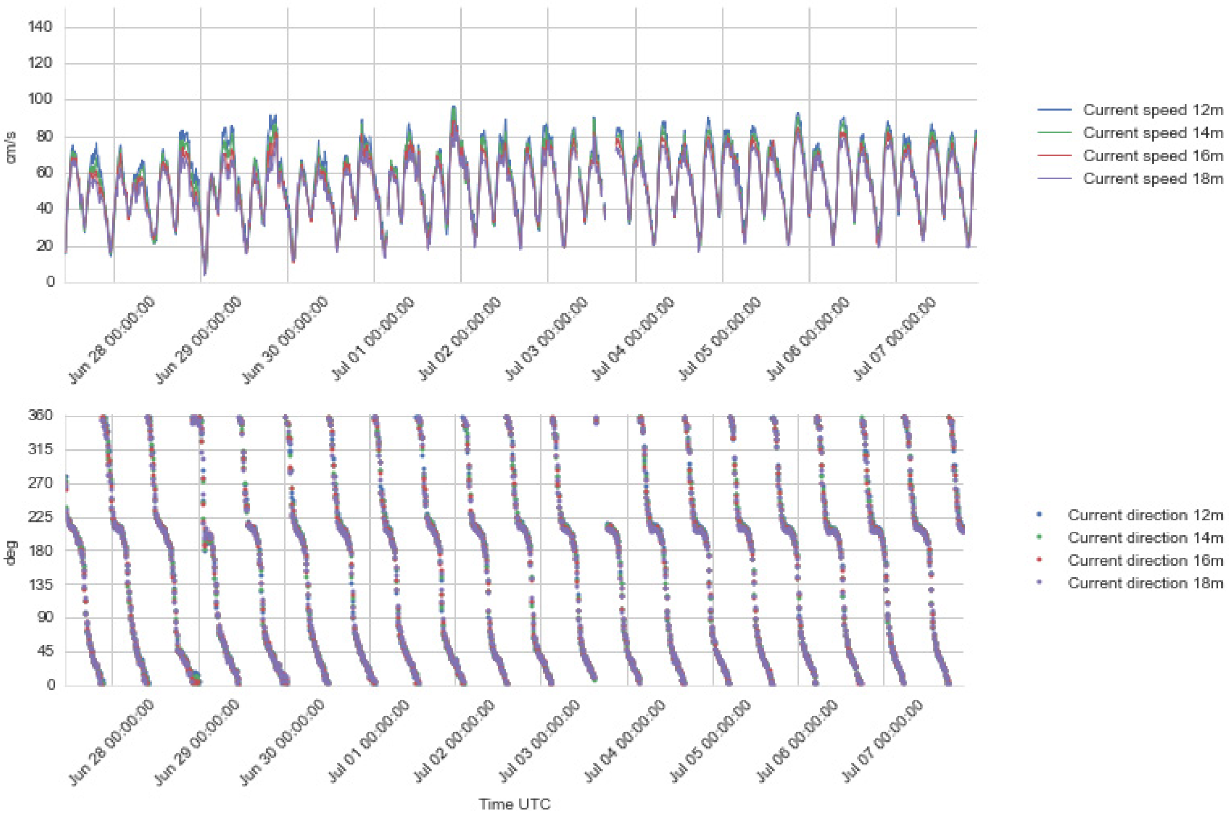

Figure 4.24 Time series plots of current speed (upper) and direction (lower panel), 12 -18 m depth, 27 Jun – 7 Jul 2016.

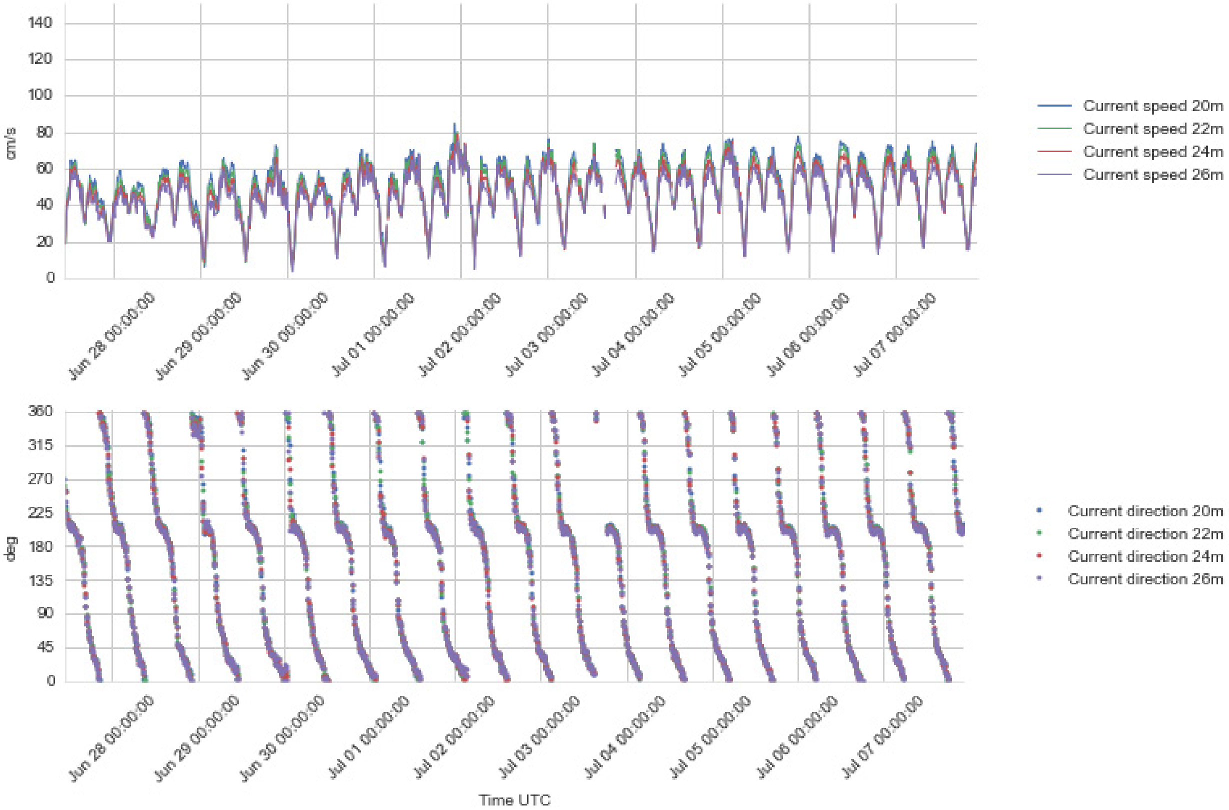

Figure 4.25 Time series plots of current speed (upper) and direction (lower panel), 20 – 26 m depth, 27 Jun – 7 Jul 2016.

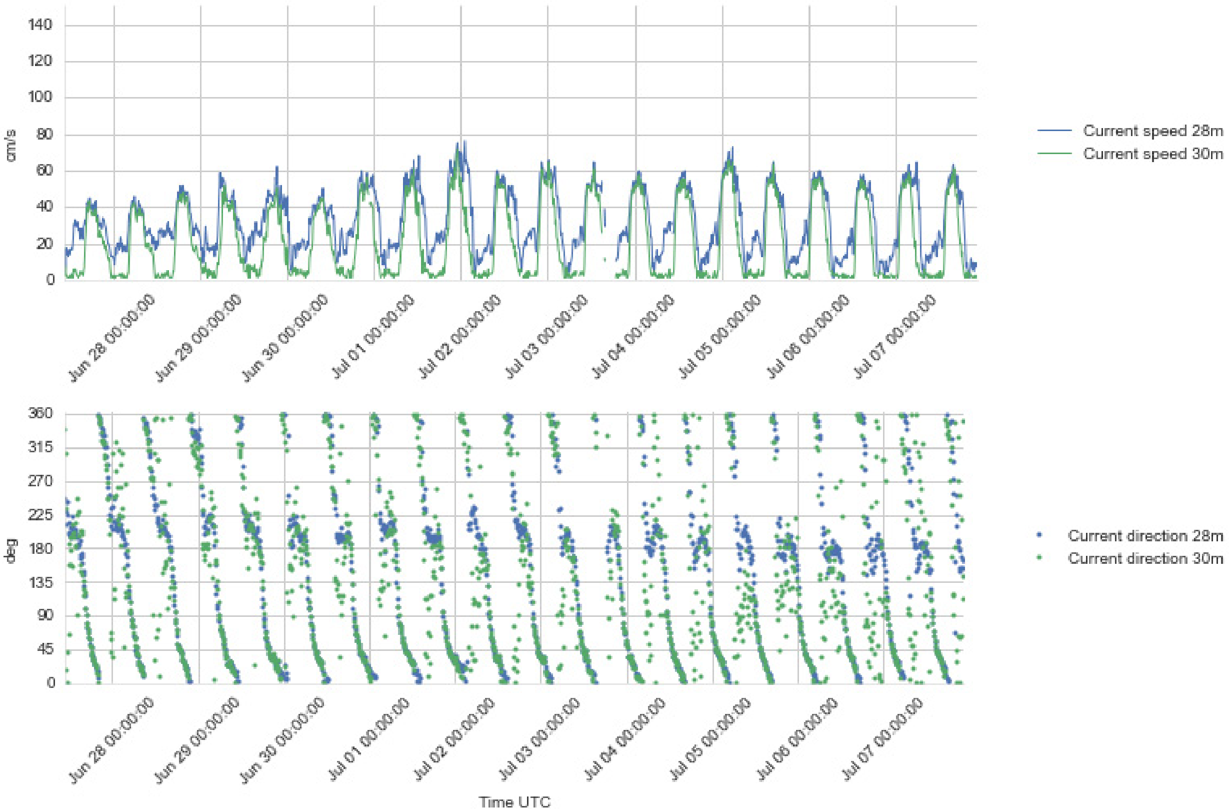

Figure 4.26 Time series plots of current speed (upper) and direction (lower panel), 28 – 30 m depth, 27 Jun – 7 Jul 2016.

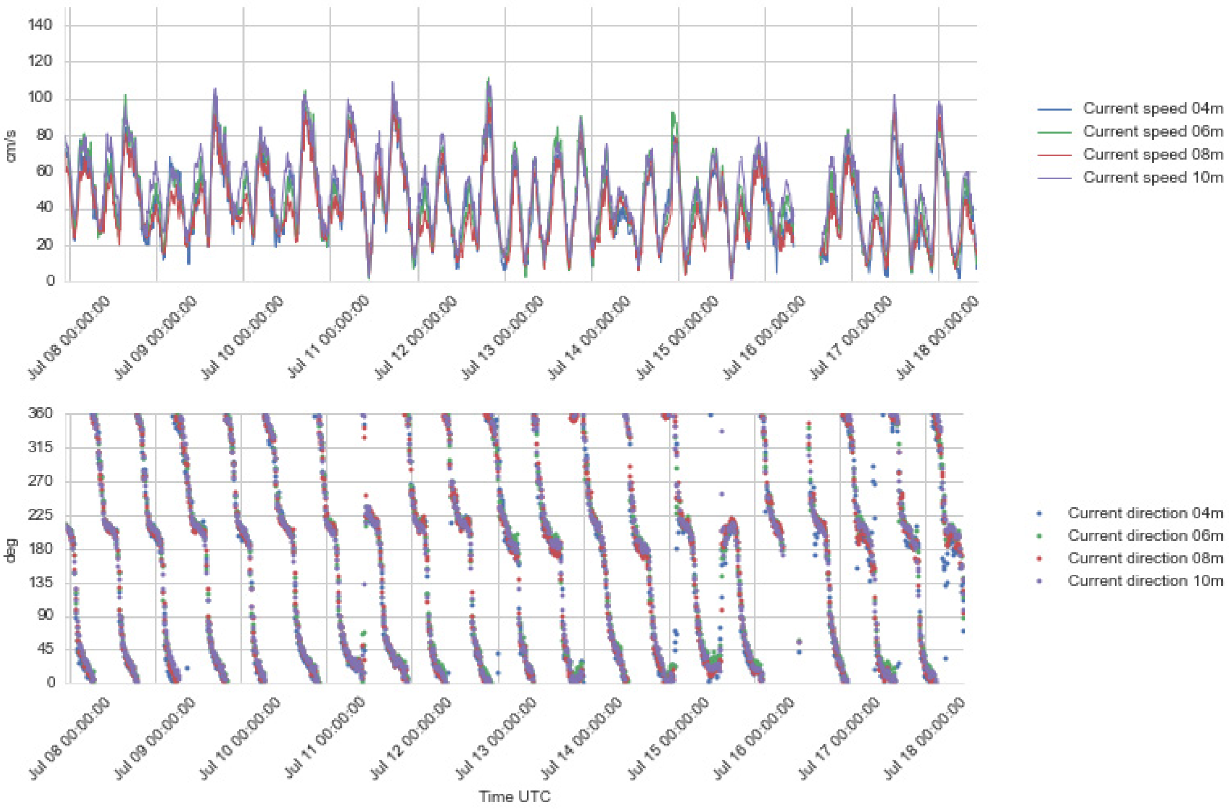

Figure 4.27 Time series plots of current speed (upper) and direction (lower panel), 4 - 10 m depth, 7 - 18 Jul 2016.

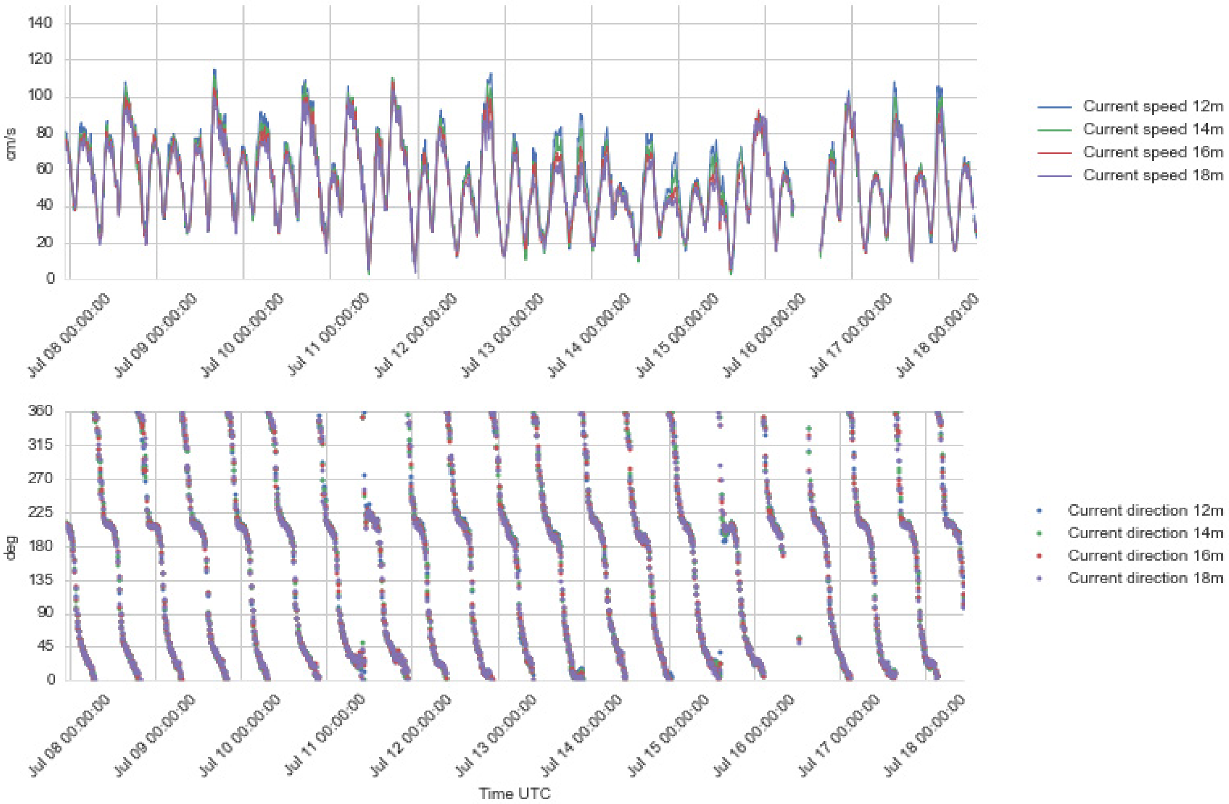

Figure 4.28 Time series plots of current speed (upper) and direction (lower panel), 12 - 18 m depth, 7 - 18 Jul 2016.

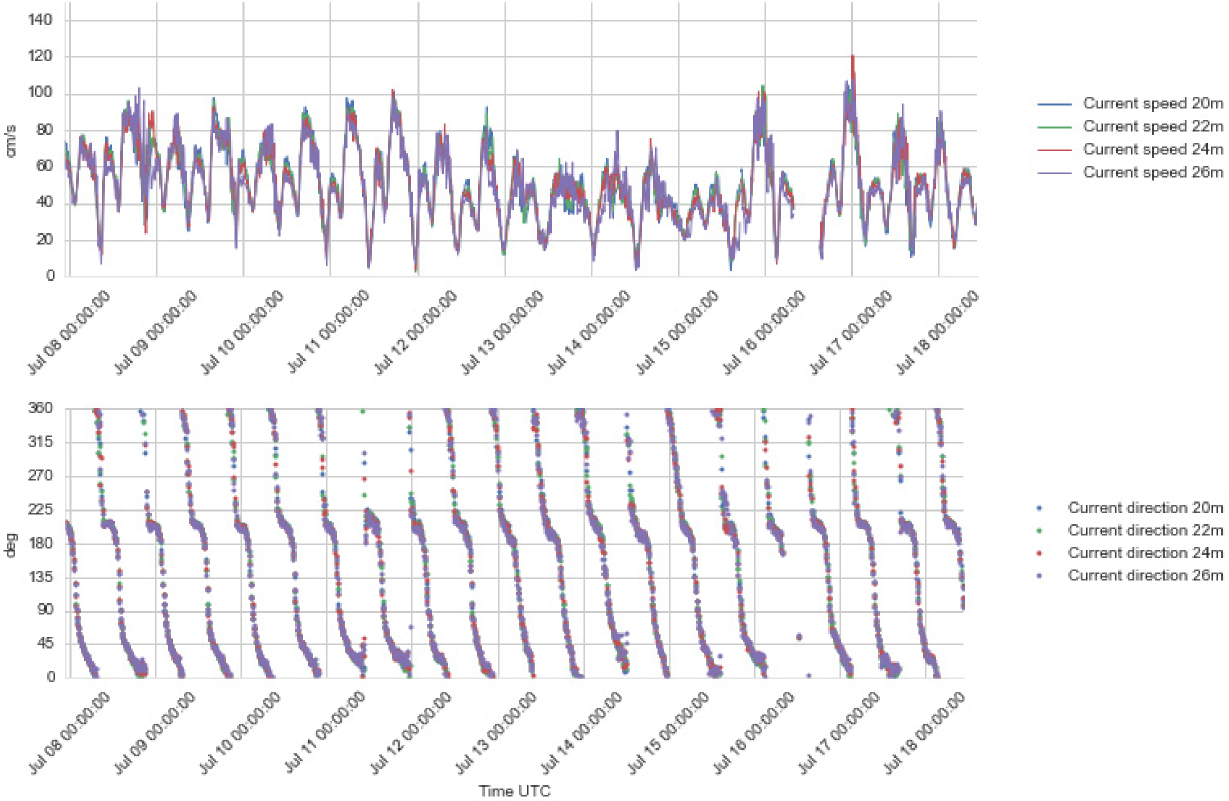

Figure 4.29 Time series plots of current speed (upper) and direction (lower panel), 20 - 26 m depth, 7 - 18 Jul 2016.

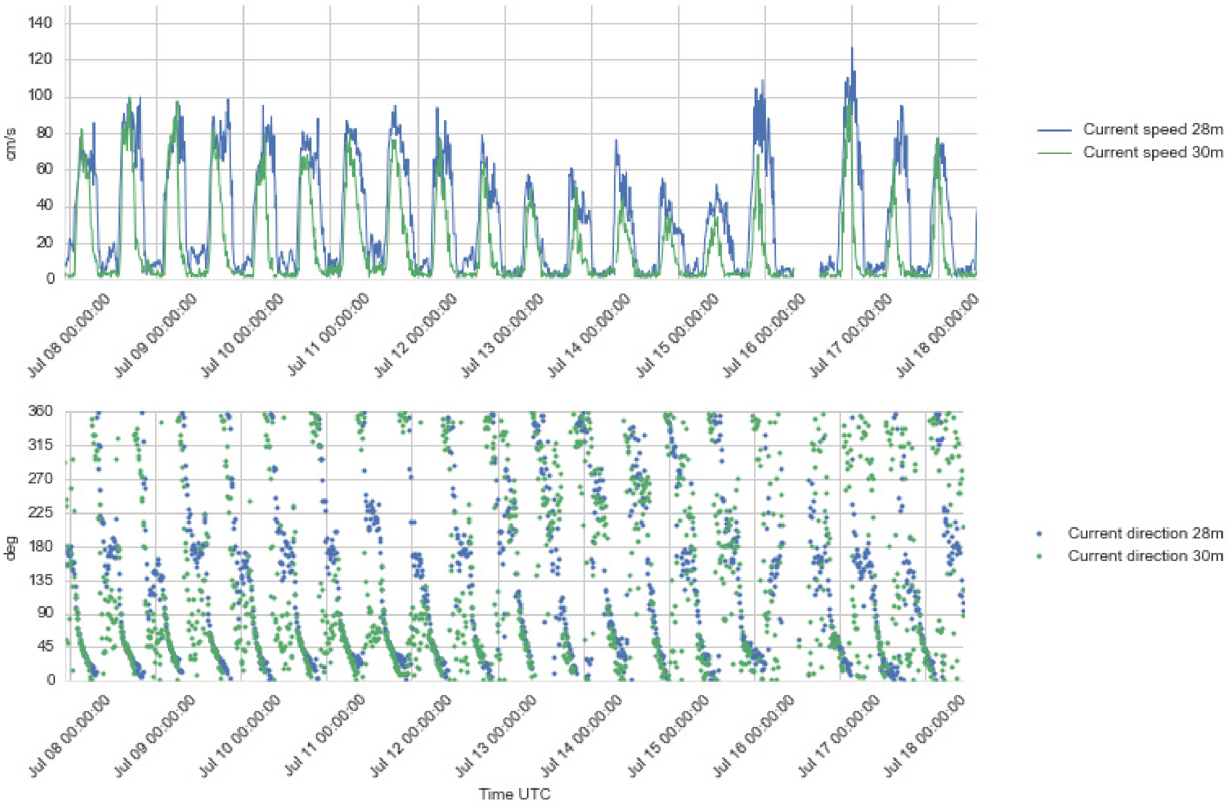

Figure 4.30 Time series plots of current speed (upper) and direction (lower panel), 28 - 30 m depth, 7 - 18 Jul 2016.

4.2.5 Water level and bottom temperature data

The buoy received no data from the bottom mounted Seaguard WLR via the acoustic data link during this month. The previously received data indicate that the communication link between the sensor and the buoy was broken on 8 July 2015. The data can be recovered from the internal storage in the WLR when it is recovered from the seabed.

Several attempts to recover the WLR have been performed without success. It is thus decided to postpone further attempts until better weather and lighter days come in the spring.

Since data recovery is of major importance, a second WLR recorder was deployed on 18 December 2015 together with the buoy to ensure data recovery. Due to long delivery times a spare acoustic communication system was not available at that time, and it was decided to deploy a WLR without the acoustics to ensure recovery of water level data. At least one of the two WLR units will record data that can be recovered from the seabed later.

Appendix A

Buoy deployment record

DEPLOYMENT/RECOVERY SHEET

Project Name:	**WS lidar buoy to Borssele-nederland**		
Project no:	C75339	Latitude:	51°42.41388'N (x=502392)
Station name:	Borssele – Lot 1	Longitude:	3°2.07708'E (y=5728440)
WS buoy no:	WS157	Approx. depth:	
PFF numbers:	33930 – 33936	Buoy marking:	

Buoy module/sensor	**Serial number/ID**
Wavesense 3 data logger	284
XSense	0770017c
PMU	252
Vaisala PTB330	L2410109
Compass	1039694
Iridium modem	IMEI: 300125060303580 SIM: 8988169514001135834 MSISDN: 881641421995 MSISDN-C: 881693413346
UHF service radio Adeunis ARF7940BA	B14500287 Addr: 11563 Remote adr: 11570
L3 AIS	S.n: 0000100117 MMSI. 992572064 Name: WIND BUOY 3
Gill wind sensor	14280085
Vaisala air HMP155 temperature/humidity	K4810054
Buoytracker	Ser.no: 766482 Name: Borssele 3 WS157
LIDAR ZephIR300	442
Flashlight	512184
Nortek Current meter	AQP6692

CONFIGURATION

Data transmission interval:	Continuous mode. ‘
Listening window	NA

POWER OPTIONS

Lead batteries type	**4 x 62Ah**
Lithium batteries:	**6 x 272Ah**
Fuel cells	**4 fuel cells with 10 methanol cartridges 28 litres each.**

DEPLOYMENT HISTORY

	YEAR	**MONTH**	**DATE**	**GMT**
First measurement	2016	2	12	12:00
First measurement in position	2016	2	12	12:30
Out of measuring position				
Last measurement				

Comments:	
Deployment vessel: Multrasalvor 3	Recovery vessel:
Deployed by:	Recovered by:

THE NETHERLANDS ENTERPRISE AGENCY (RVO)

Supply of Meteorological and Oceanographic data at Borssele Wind Farm Zone (BWFZ)
Validation report: 16 June - 18 July 2016

Reference No: C75339_VAL09_R1
15 August 2016

Fugro OCEANOR AS
Pirsenteret, P.O. Box 1224, Sluppen, N-7462 Trondheim, Norway
Tel: +47 73545200 Fax: +47 73545201, e-mail: trondheim@oceanor.com

Supply of Meteorological and Oceanographic data at Borssele Wind Farm Zone (BWFZ): C75339_VAL09_R1				
Rev	**Date**	**Originator**	**Checked & Approved**	**Issue Purpose**
0	26.07.2016	Lasse Lønseth	Olaf Sveggen	Final report
1	15.08.2016	Lasse Lønseth	Arve Berg	Final report, revised after review

Rev 1 – 15 August 2016	Originator	Checked & Approved
Signed:	Lasse Lønseth	Arve Berg

This report is not to be used for contractual or engineering purposes unless the above is signed where indicated by both the originator of the report and the checker/approver and the report is designated 'FINAL'.

TABLE OF CONTENT

SUMMARY 1

1. INTRODUCTION 2

2. Instrumentation and measurement configuration 2

3. Results 6
   3.1 Data recovery 6
   3.2 Reference stations 6
      3.2.1 Positions and distances 6
      3.2.2 Schouwenbank 7
      3.2.3 Vlakte van de Raan 8
   3.3 Evaluation of the collected data 9
      3.3.1 Wave data 9
      3.3.2 Wind data 12
   3.4 Conclusions 15

Appendix A: Buoy deployment record

SUMMARY

The Seawatch Wind Lidar buoy is deployed at the Borssele Wind Farm Zone (BWFZ). The buoy was first deployed on 11 June 2015 at 15:55 UTC, and a bottom mounted tide gauge (WLR) was deployed at 16:15 UTC on the same day. The buoy transmitted data continuously until transmissions stopped on 11 September, and it was recovered on 6 October 2015. The buoy was then repaired, and re-deployed on 12 November 2015. The Lidar stopped working on 26 December 2015 due to a technical problem, while the buoy continued measuring and transmitting data from all other sensors. The buoy was recovered for repair on 19 January 2016. The spare buoy was deployed at the same position in the BWFZ on 12 February 2016 and is currently in operation.

This report presents an evaluation of the wind and wave data collected during the period 16 June – 18 July 2016, comparing the buoy data to data from two fixed measurement stations in the region. The reference station for wave measurements is a Waverider buoy at Schouwenbank (station SCHB), and the reference for wind measurements is the platform at Vlakte van de Raan (VR).

Although the reference stations are some 19 – 26 km away from the buoy location we see good agreement between the buoy and references.

1. INTRODUCTION

A Seawatch Wind Lidar buoy is deployed at the Borssele Wind Farm Zone (BWFZ) in the Dutch sector of the North Sea. The buoy with serial no. WS149 was first deployed on 11 June 2015 at 15:55 UTC with the bottom mooring weight at position 51° 42.41388’ N, 3° 2.07708’ E. A bottom mounted water level recorder (WLR) at position 51° 42.4362’ N, 3° 02.1030’ E transmits data to the buoy in real time data via an acoustic link. The water depth at this location is approximately 30 m.

Following the stop in the transmissions from the buoy on 11 September 2015 at 16:00, the buoy was recovered to shore on 6 October 2015 for inspection and repair. It was redeployed after repair on 12 November 2015 at 14:00.

The Lidar on Buoy WS149 stopped working on 26 December 2015 due to a technical problem with its power switch. After a long period of mainly unworkable weather conditions, and some delay due to vessel unavailability, the buoy was recovered for repair on 19 January 2016. The buoy was replaced by the spare buoy WS157, which was deployed on 12 February 2016 at 13:00. This buoy has since collected good data, and the wind and wave data collected during the period 16 June – 18 July 2016 are presented in the data presentation report ref. C75339_MPR09_R0.

This report presents an evaluation of the wind and wave data collected in the period 16 June – 18 July 2016, comparing the buoy data to data from fixed measurement stations in the area. The reference stations used in this report are the Waverider buoy at Schouwenbank (station SCHB) for waves, and a platform with a wind sensor at Vlakte van de Raan (VR) for wind measurements. The comparisons are shown in time series and scatter plots.

The time reference used in this report is UTC.

2. Instrumentation and measurement configuration

The buoy is a Seawatch Wind Lidar Buoy based on the original Seawatch Wavescan buoy design with the following sensors:

- Wavesense: 3-directional wave sensor
- Xsens 3-axes motion sensor
- Gill Windsonic M acoustic wind sensor
- Vaisala PTB330A air pressure sensor
- Vaisala HMP155 air temperature and humidity sensor
- Nortek Aquadopp 600kHz current profiler.
- ZephIR 300S Lidar.

An independent self-recording Aanderaa SeaGuard WLR tide gauge is located on the bottom. The WLR transmits data to the buoy via an acoustic link.

The buoy with mooring as deployed is presented in Figure 2.1, including the mooring for the WLR.

The measurement setup is detailed in Table 2.1. Detail information such as sensor types and serial numbers can be found in the deployment record in Appendix A.

Table 2.1 Configuration of measurements by the Seawatch Wind Lidar buoy at Borssele Borssele Wind Farm Zone (BWFZ).

Instrument type	Sensor height (m)	Parameter measured	Sample height[2)] (m)	Sampling interval (s)	Averaging period (s)	Burst interval (s)	Trans-mitted?
Wavesense 3	0	Heave, pitch, roll, heading	0	0.5	Time series duration: 1024 s	600	No
		Sea state parameters (1)	0	600	1024	600	Yes
Xsens		Heave,east,north acceleration, q0,q1,q2,q3 (attitude quaternion)	0	0.5	N/A	3600	No
Gill Windsonic M	4.1	Wind speed, wind direction	4.1	1	600	600	Yes
Vaisala PTB330A	0.5	Air pressure	0.5	30	60	600	Yes
Vaisala HMP155	4.1	Air temperature Air humidity	4.1	5	60	600	Yes
Nortek Aquadopp	-1	Current speed and direction profile, water temperature (at 1 m depth)	-4 -6 … -30 (14 levels)	N/A	600	600	Yes
ZephIR 300S Lidar	2	Wind speed and direction at 10 heights (The 11th level, the so called reference level which is not configurable, is also located at 40 m and referred to as 40.0 Ref.)	30.0 40.0 40.0 ref 60.0 80.0 100.0 120.0 140.0 160.0 180.0 200.0	≈ 17.4 s[1)]	600	600	Yes
Aanderaa WLR (SeaGuard) via acoustic link	-30	Water pressure Temperature	-30	600	60	600	Yes[3)]

1) This is the approximate time between the beginning of one sweep of the profile and the next one, the interval may vary slightly. The ZephIR sweeps one level at a time beginning at the lowest one, and after the top level has been swept it uses some time for calculations and re-focusing back to the lowest level for a new sweep.

2) Height relative to actual sea surface. The depth of the WLR is an approximate number.

3) The WLR data are not transmitted after 8 July 2015 due to failure of the acoustic link. An additional self-contained WLR was deployed 18 December 2015 to ensure data recovery.

Table 2.2 Definitions of wave parameters presented in this report

H	Individual wave height
Hmax	= Max(H): Height of the highest individual wave in the sample, measured from crest to trough
m0, m1, m2, m4, m-1, m-2	Moments of the spectrum about the origin: $\int f^k S(f)df$ where $S(f)$ is the spectral density and the wave frequency, f, is in the range 0.04 - 0.50 Hz
Hm0	Estimate of significant wave height, Hs, $Hm0 = 4\sqrt{m0}$
Tp	Period of spectral peak = $1/f_p$, The frequency/period with the highest energy
Tm01	Estimate of the average wave period; $Tm01 = m0/m1$
Tm02	Another estimate of the average wave period; $Tm02 = \sqrt{\frac{m0}{m2}}$
ThTp	Mean wave direction at the spectral peak (“The direction of most energetic waves”)
Mdir	Wave direction averaged over the whole spectrum
	Directions are given in degrees clockwise from north, giving the direction the waves come from. (0° from north, 90° from east, etc.)

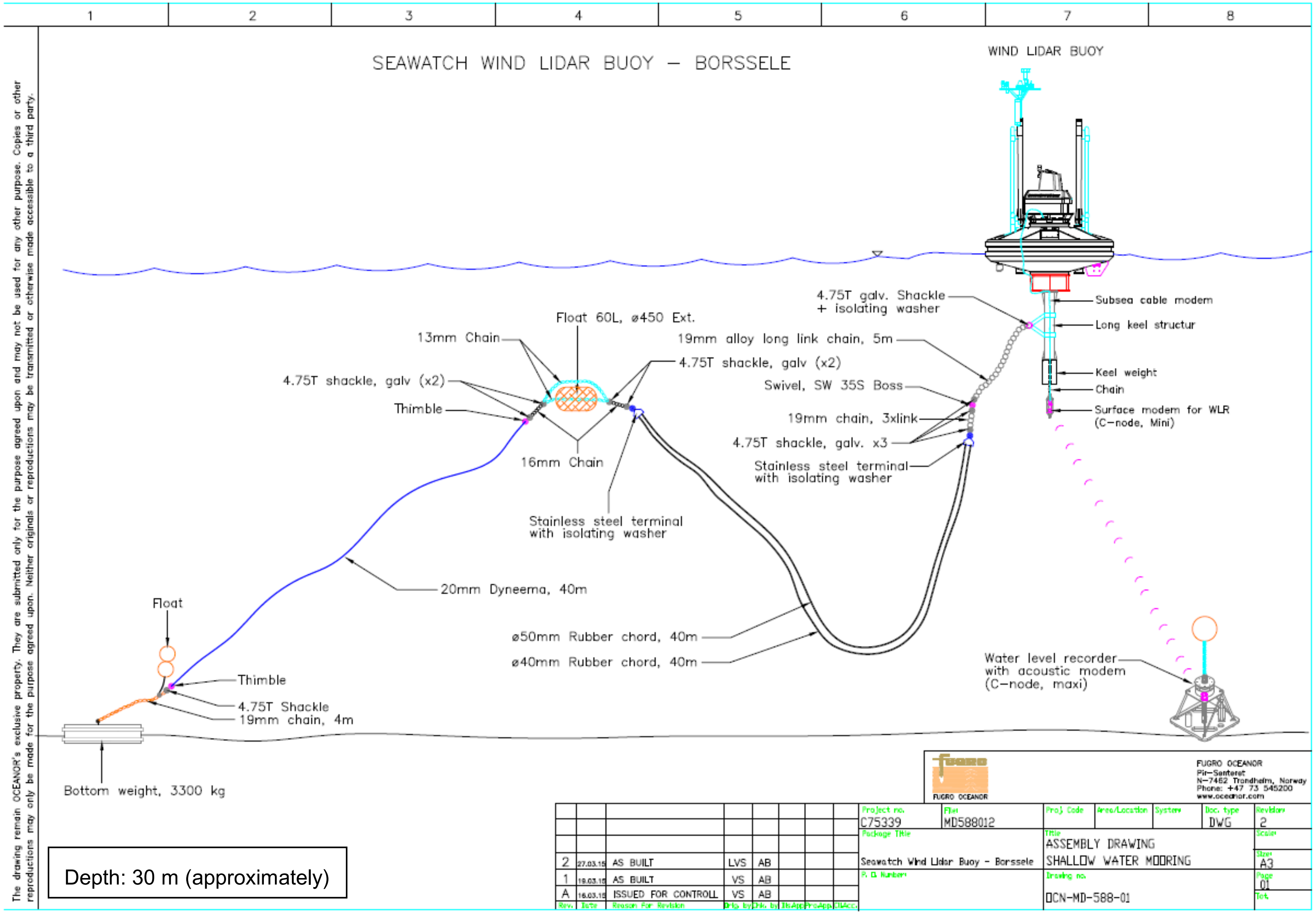

Figure 2.1 Mooring design for the Wind Lidar Buoy as deployed at Borssele Wind Farm Zone (BWFZ).

3. Results

3.1 Data recovery

The buoy transmitted data continuously from all sensors from 16 June 2016 at 22:50 until 18 July 2016 at 10:20, with the exception of some minor gaps. There are a few short gaps in the Lidar data where the received data are replaced by the “missing data” flag at all heights. The gaps are mainly short dropouts where 1-2 records are missing in the Lidar data only. The longer gaps in the Lidar data lasted from 00:00 to 01:00 on 21 June, from 16:00 to 19:00 on 3 July, and the longest outage occurred on 16 July from 09:00 to 09:30, and from 10:00-14:20. During the latter data gap the data are missing from all sensors on the buoy, and it appears that the data collection restarts to run normally after an automatic restart of the buoy system. Due to the gaps it took 31.486 days to collect 30.5 days of good wind profile data[1].

The number of hours of good data compared to the total obtainable hours of data is presented in Table 3.1.

Table 3.1 Data return during the period 16 June 2016 at 22:50 – 18 July 2016 at 10:20.

Measurement device	Length of data period (days)	Length of data set (days)	Average availability (%)
Lidar wind profile sensor	31.486	30.500	96.87
Wave sensor	31.486	30.951	98.24
Current velocity sensor	31.486	31.139	98.83
Atmospheric pressure sensor	31.486	31.153	98.88
Air temperature sensor	31.486	21.875	69.43
Water Level Sensor *	31.486	0.000	0.00

* The real time transmitted water level data are unexpectedly lost due to breakdown of the acoustic link. However, the complete data series will be recovered if the instrument is recovered.

3.2 Reference stations

3.2.1 Positions and distances

Two public reference stations are used in the validation of the data. The reference for the wave measurements is a Waverider buoy at Schouwenbank (SCHB). For wind the reference is the station at Vlakte van de Raan (VR). The positions of the stations are given in Table 3.2, which gives an overview of the locations and distances.

[1] Additional gaps in the real time transmitted Turbulence Intensity (TI) data are caused by breaks in the satellite dial-up transmission link. The data that were not received in real time are stored internally in the buoy and will be downloaded from the buoy when it is recovered.

Table 3.2 Positions of the Lidar buoy and the reference stations used in the evaluation of the buoy data.

Station	Latitude	Longitude	Distance from the Lidar buoy	Shortest distance from land
Borssele Lidar buoy	51° 42.41' N	3° 2.08' E		32.5 km
Schouwenbank Waverider buoy (SCHB)	51° 44.8' N	3° 18.3' E	19.3 km	22.0 km
Vlakte van de Raan (VR)	51° 30.0' N	3° 15.0' E	27.6 km	12.2 km

3.2.2 Schouwenbank

The wave measuring buoy at Schouwenbank (SCHB station) is a directional ("2D") Datawell Waverider buoy. This buoy measures the wave height and directional spectrum using 3-axis accelerometers.

The SCHB station should be expected to have lower heights of wind sea than the Borssele Lidar buoy location in southerly to north-easterly winds due to the more limited fetch distance in those directions. In situations with wind sea from north-east to north-west, and situations dominated by northerly swells the two buoy should be exposed to approximately the same wave heights.

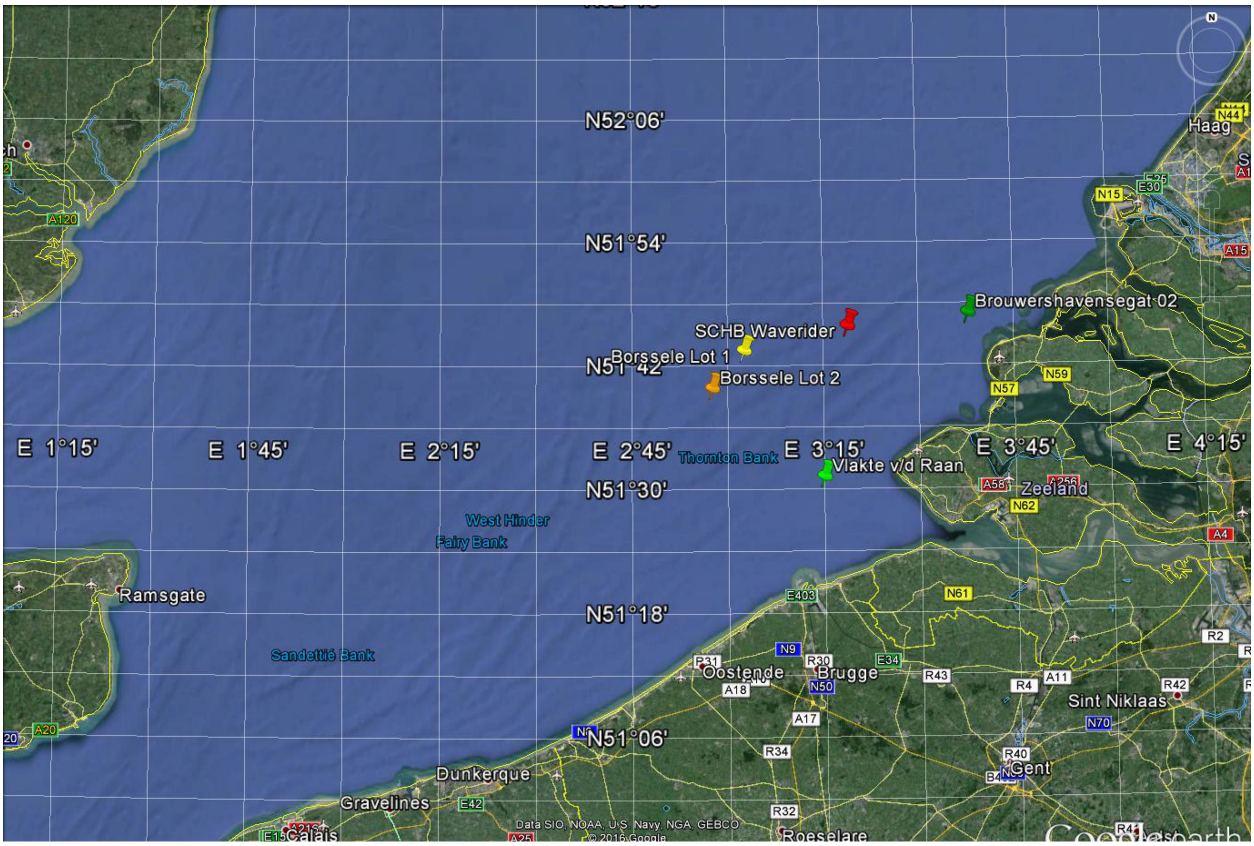

Figure 3.1 Google Earth image indicating Lidar buoy Lot 1 and 2 positions and reference stations. (The Borssele Lot 1 Lidar buoy which is validated in this report is marked by the bright yellow pin.)

3.2.3 Vlakte van de Raan

The Vlakte van de Raan (VR) station is measuring wind speed and wind direction. Figure 3.2 shows a photo of the wind mast. Wind speed is measured with the KNMI cup-anemometer. Cup diameter is 105 mm and the distance between the centre of the cups to the rotation axis is 100 mm. Wind direction is measured with the KNMI wind vane. Distance between axis and the outer side of the vane is 535 mm. The anemometer and wind vane are located 13.9 m above the mean sea level. The azimuth of the wind vane plugs at the tip of the booms are determined with a camera relative to distant objects at close to the horizon. The instruments are logged with the KNMI wind SIAM. Wind gusts are determined from a running 3 sec mean value.

Figure 3.2 The wind measuring station at Vlakte van de Raan.

Calibration of the cup anemometers is done in the wind tunnel of KNMI. Wind vanes are balanced and the direction of the vane is tested. Sensors are replaced after 26 month. The cup anemometer contains a photo-chopper with 32 slits. The accuracy is 0.5 m/s. The treshold velocity is 0.5 m/s. The resolution is

0.1 m/s. The response length is 2.5 m. The wind vane contains a code disk. Accuracy is 3°. Resolution is 1°. [ref. Chapter 5 “Handbook for the Meteorological Observation. Koninklijk Nederlands Meteorologisch Instituut KNMI, De Bilt September 2000.]

The VR station is located only 12 km from the coast and much closer to land than the Lidar buoy, and that is expected to have some effect on the winds, both speed and direction, especially for wind with direction from shore; directions from south-southwest to east-northeast in particular. This means that there can be considerable differences in wind speed and direction at any given time, while the long term overall averages are expected to be approximately the same.

3.3 Evaluation of the collected data

3.3.1 Wave data

The wave data from the Lidar buoy are compared to data from the Waverider at Schouwenbank in time series and scatter plots. The distance of about 20 km between the two locations and the different distance from shore is expected to cause some differences in these shallow waters.

The time series plot in Figure 3.3 and scatter plot in Figure 3.4 compare the significant wave height (Hm0). All peaks in the time series occur at almost exactly the same time, showing good coherence. The average Hm0 values are 0.94 m at the Lidar buoy compared to 0.90 m at Schouwenbank. The difference as well as the scatter with R^2 = 0.939 may be attributed to differences between the locations. The water depth is different at the two locations, with SCHB being the shallower, and this would explain why the wave height is systematically lower at SCHB compared to the Lidar buoy at higher sea states, while they are the same at low sea states. The different distance from shore would give lower waves at SCHB when there is wind from shore due to the more limited fetch. Keeping this in mind we see that the Lidar buoy data compares remarkably well to the reference.

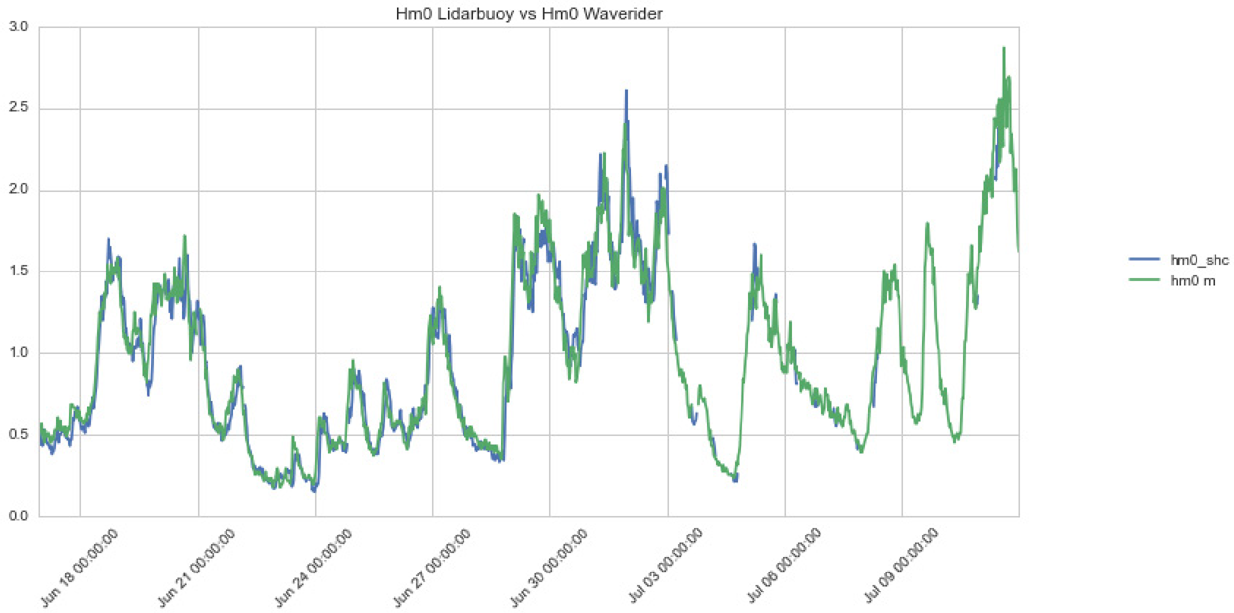

Figure 3.3 Time series plot of significant wave height (Hm0) from the Lidar buoy (green curve) and the Schouwenbank Waverider buoy (blue).

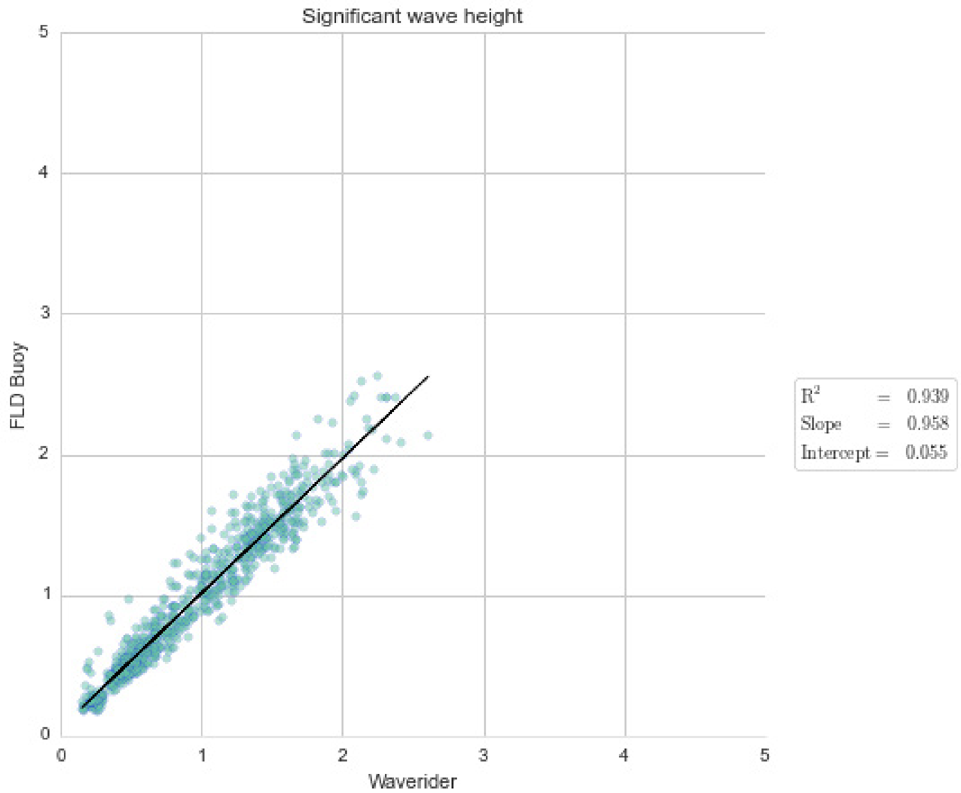

Figure 3.4 Scatter plot comparing Hm0 measured by the Lidar buoy to Hm0 from the Schouwenbank Waverider buoy.

The mean wave period (Tm02) from the Lidar buoy is compared to the Waverider Tm02 in the time series plot in Figure 3.5 and the scatter plot in Figure 3.6. The time series plot shows good coherence and the values appear very similar. The scatter plot shows R^2 = 0.83. Some scatter must be expected due to the distance between the stations. The average values of Tm02 are 4.08 s at the Lidar buoy compared to 4.01 s at the Waverider.

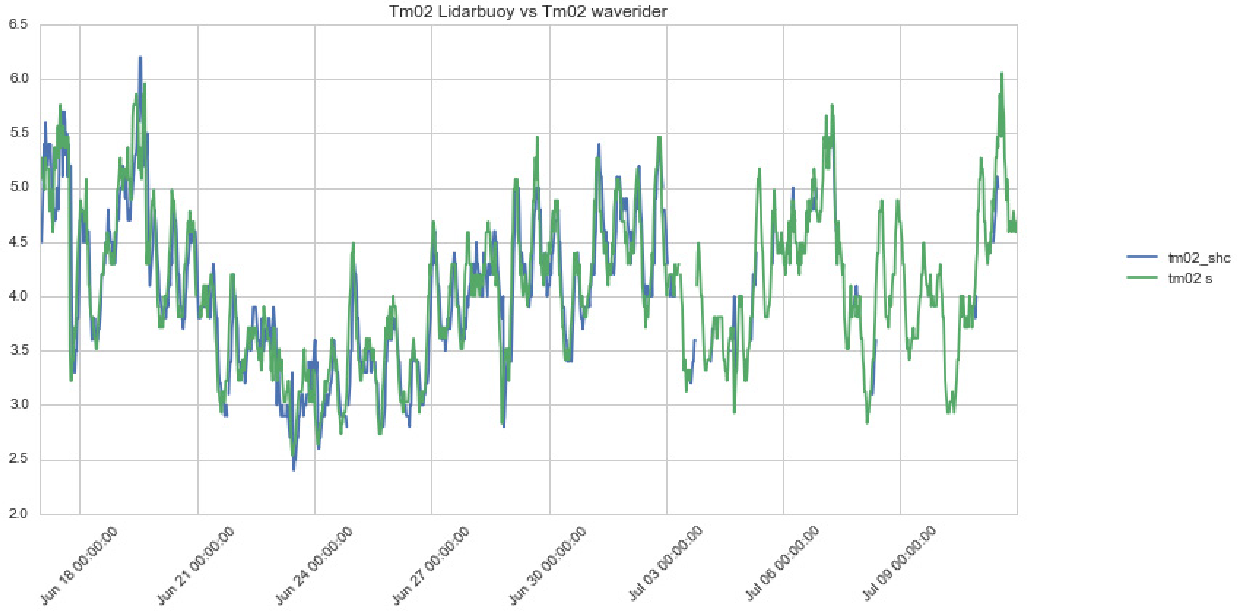

Figure 3.5 Time series plot of mean wave period (Tm02) from the Lidar buoy (green curve) and the Schouwenbank Waverider buoy (blue).

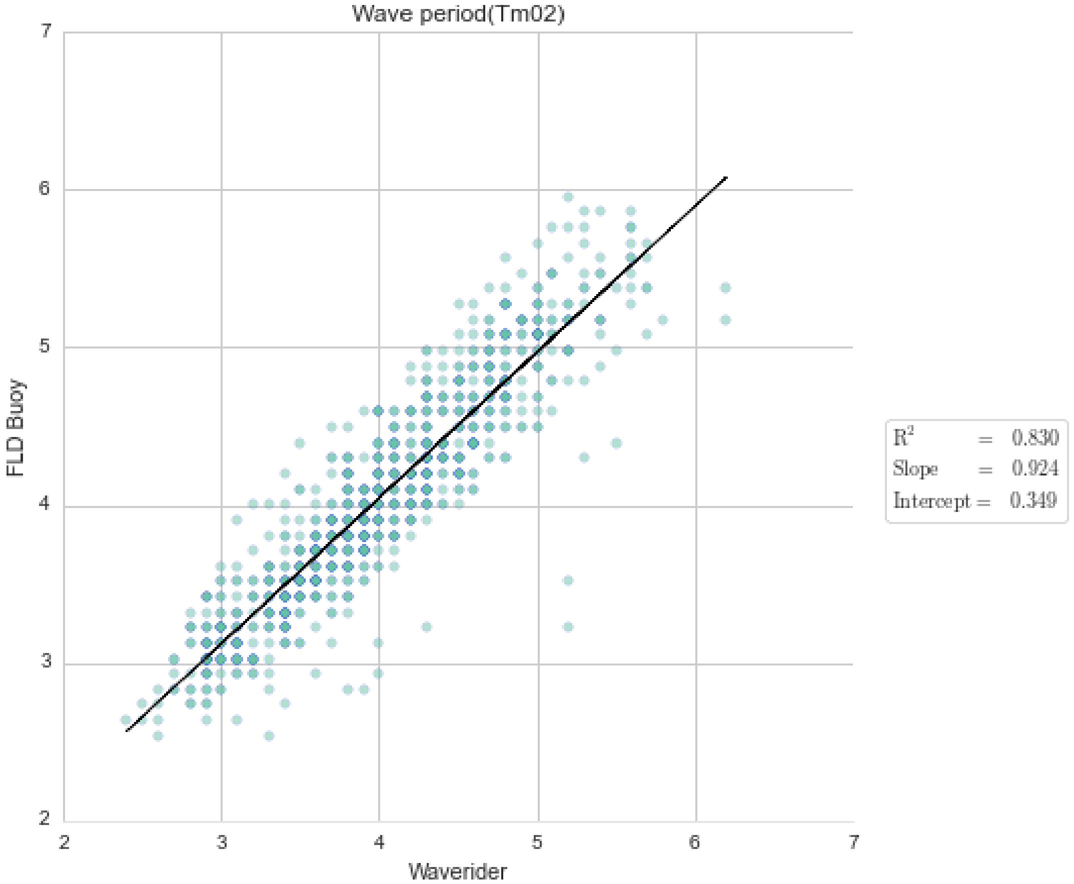

Figure 3.6 Scatter plot comparing Tm02 measured by the Lidar buoy toTm02 from the Schouwenbank Waverider buoy.

3.3.2 Wind data

The Vlakte van de Raan (VR) wind station is located about 28 km away from the Lidar buoy and much closer to shore. The VR station is about 12 km from the nearest shore, while the buoy is 33 km from land. The wind speeds measured at anemometer height, 13.9 m above the mean sea level, have been reduced to 10 m above mean sea level by a factor of 0.95. The horizontal Lidar wind speed data from the lowest cell, at 30 m above the sea surface, have been compared to the wind data from VR adjusted from 10 m to 30 m height by a factor of 1.15. The data series presented in Figure 3.7 show a similar behaviour as the maxima in wind speed at both locations appear at the same time, showing good coherence. On average the buoy show lower average speed at 30 m height than the VR station, the values are 7.59 m/s at the buoy and 8.15 m/s at VR.

The scatter plot in Figure 3.8 compares the wind speeds when the VR station speeds exceed 2 m/s. The correlation is seen clearly. The large scatter and the slope of 0.9 in the regression line is probably due to the distance between the stations and the differences in the way land effects influence the local wind. This confirms that there is no reason to suspect that the Lidar has not measured the wind speed correctly.

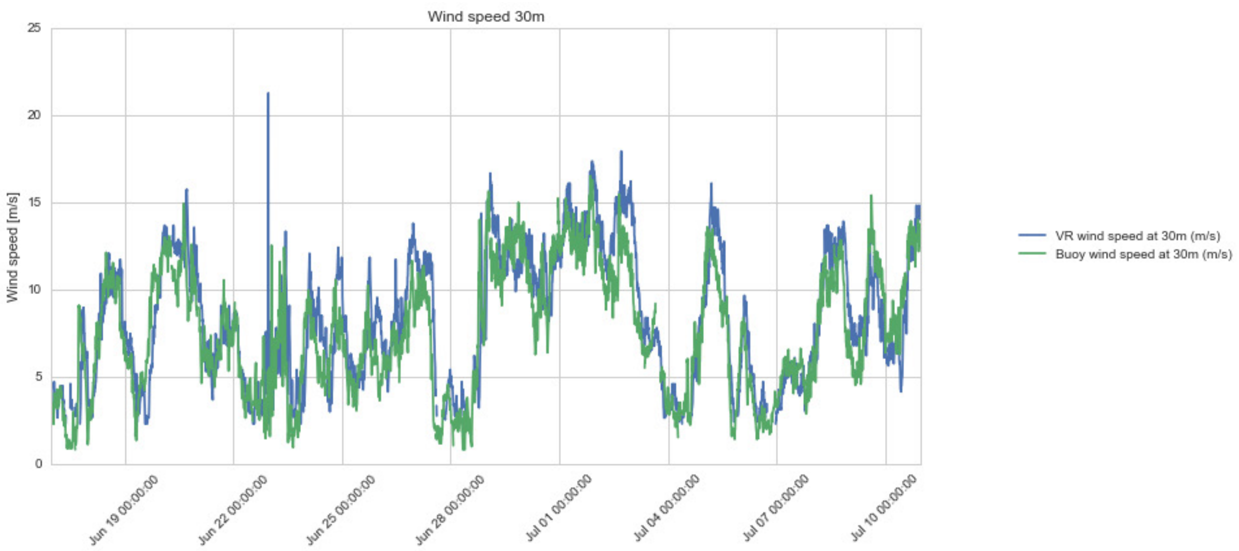

Figure 3.7 Wind speed at 30 m above sea level measured by the Lidar buoy (green curve) compared to wind speed at Vlakte van de Raan adjusted to 30 m (blue).

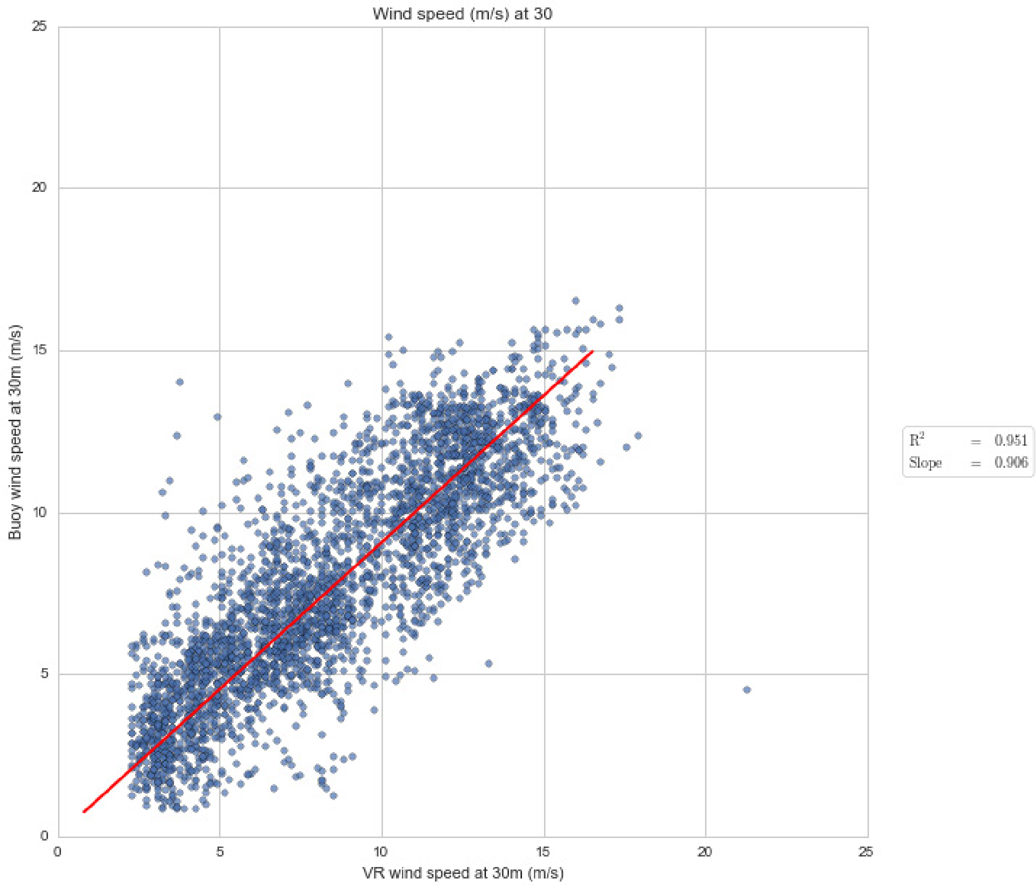

Figure 3.8 Scatter plot comparing the wind speed at 30 m above sea level measured by the Lidar buoy to the wind speed at Vlakte van de Raan adjusted to 30 m a.s.l. (Regression formula: y = Slope * x)

The time series of wind direction are compared in Figure 3.9, which also shows the wind speed at Vlakte van de Raan. Samples with speed less than 2 m/s are excluded. Again we see that there is a general agreement between the measurements, and this is seen also in the scatter plot in Figure 3.10. The offset between the wind directions is calculated as the average of the difference between the wind directions. It should be expected that the wind directions differ at any given time due to the distance between the locations, and this explains the scatter seen in the plot. The average offset of 16.5° is not thought to indicate a fault in the buoy, but rather to be caused by real differences connected to the situation of the buoy and reference stations relative to land and the weather patterns. The Lot 1 and Lot 2 buoys show approximately the same directional offset versus the VR directions. The plot in Figure 3.10 shows that the dominating wind directions in this period were in the sector between south and west, with a secondary concentration of observations from north-west. It shows a clear offset in both those sectors, but largest when the VR station shows wind from WSW, which gives the wind a component toward the coast. In previous periods it was noted that the offset was small for N-NE wind directions, but in this period there are few observations of wind from that sector. However, in this period there were many low pressures and fronts passing that might give an offset in directions, and we conclude that the data do not give reason to suspect that buoy wind directions are faulty.

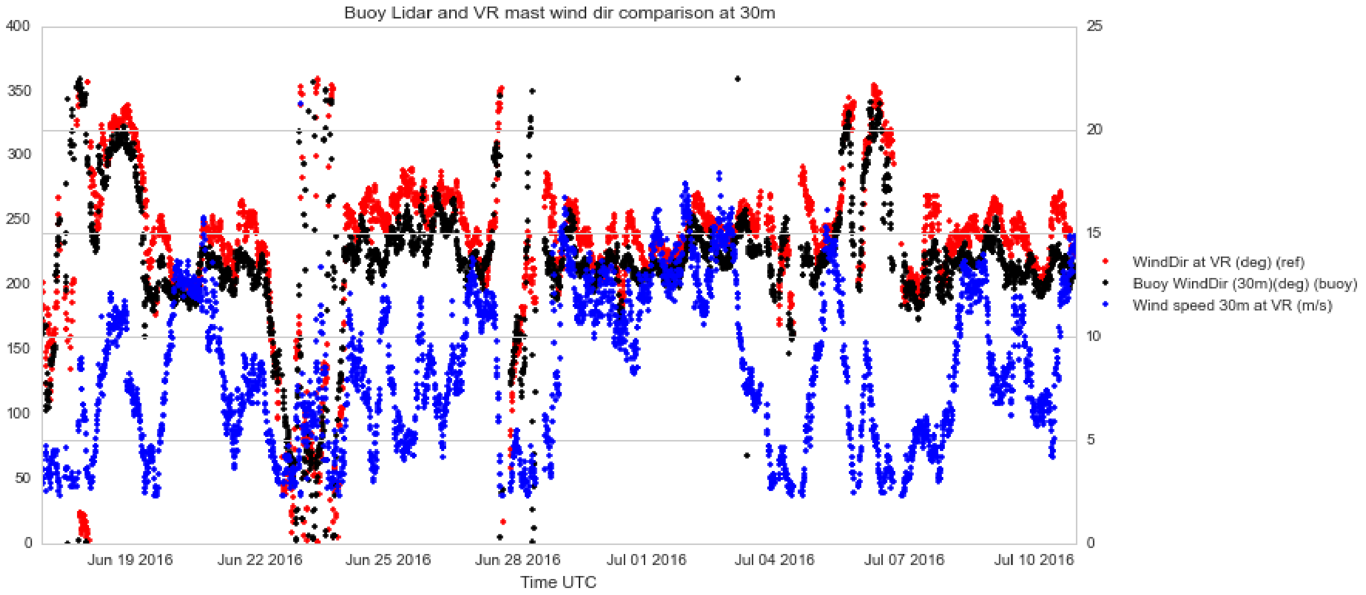

Figure 3.9 Wind direction at 30 m above sea level measured by the Lidar buoy (black dots) compared to wind direction at Vlakte van de Raan. (red). The blue dots show the VR station 10m wind speeds. (Samples with VR wind speed less than 2 m/s are excluded.)

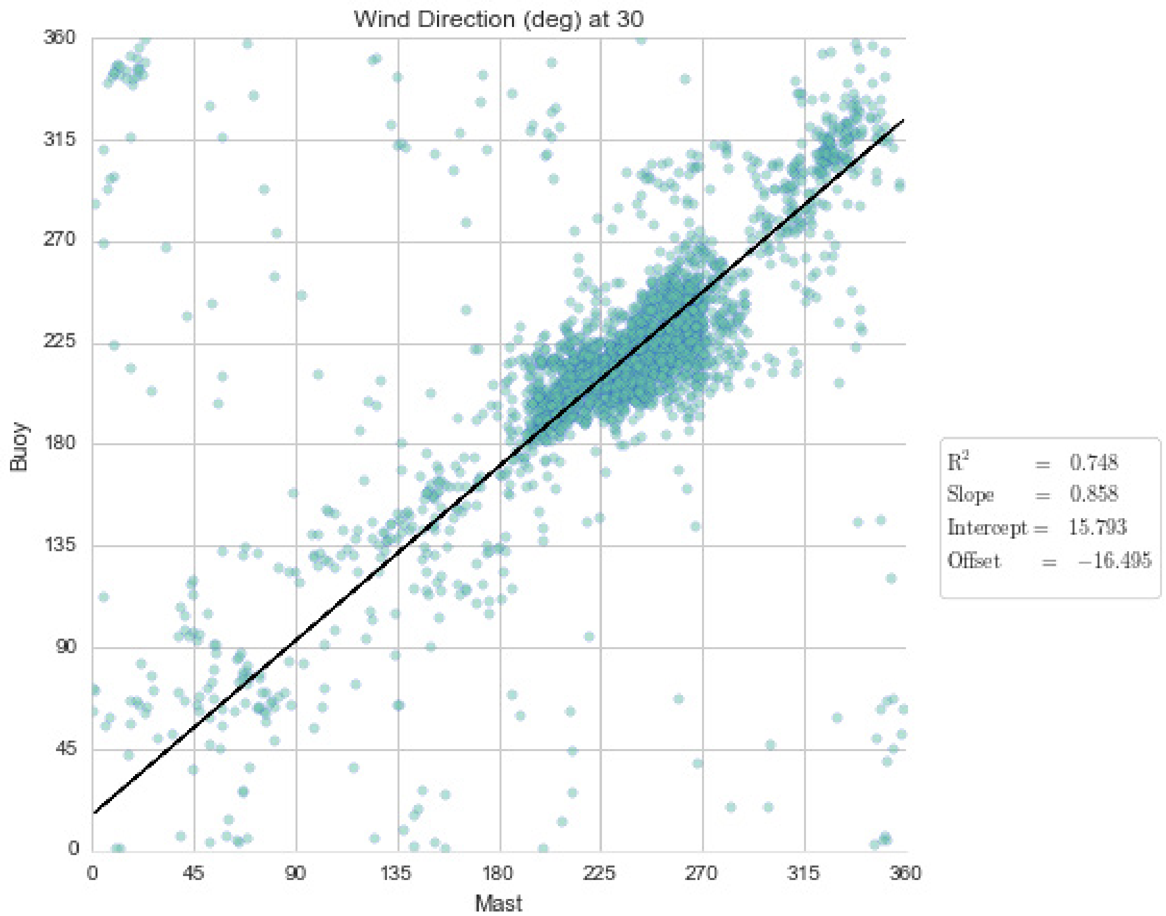

Figure 3.10 Wind direction at 30 m above sea level measured by the Lidar buoy compared to wind direction at Vlakte van de Raan.. (Samples with VR wind speed less than 2 m/s are excluded.) ("Offset" is the average difference of directions.)

3.4 Conclusions

The comparisons to the reference station data presented above indicate that the buoy has collected data of good quality for winds and waves. The Seawatch Wind Lidar buoy has transmitted data almost continuously during the month, but there was one break of about 4 hours in the transmissions. In addition there are a few short gaps in the Lidar data with a duration of 1 hour or less where the received data are replaced by the “missing data” flag at all heights. Due to the gaps it took 31.486 days to collect 30.5 days of good wind profile data.

Appendix A

Buoy deployment record

DEPLOYMENT/RECOVERY SHEET

Project Name:	**WS lidar buoy to Borssele, Nederland**		
Project no:	C75339	Latitude:	51°42.41388'N (x=502392)
Station name:	Borssele – Lot 1	Longitude:	3°2.07708'E (y=5728440)
WS buoy no:	WS157	Approx. depth:	
PFF numbers:	33930 – 33936	Buoy marking:	

Buoy module/sensor	**Serial number/ID**
Wavesense 3 data logger	284
XSense	0770017c
PMU	252
Vaisala PTB330	L2410109
Compass	1039694
Iridium modem	IMEI: 300125060303580 SIM: 8988169514001135834 MSISDN: 881641421995 MSISDN-C: 881693413346
UHF service radio Adeunis ARF7940BA	B14500287 Addr: 11563 Remote adr: 11570
L3 AIS	S.n: 0000100117 MMSI. 992572064 Name: WIND BUOY 3
Gill wind sensor	14280085
Vaisala air HMP155 temperature/humidity	K4810054
Buoytracker	Ser.no: 766482 Name: Borssele 3 WS157
LIDAR ZephIR300	442
Flashlight	512184
Nortek Current meter	AQP6692
Fuel Cell 1	efoy : 302305-1443-34660 stack: 151010084-01188
Fuel Cell 2	efoy : 302306-1536-36836 stack: 151010086-00093
Fuel Cell 3	efoy : 302305-1443-34656 stack: 151010084-01190
Fuel Cell 4	efoy : 302305-1443-34647 stack: 151010084-01179

CONFIGURATION

Data transmission interval:	Continuous mode. ‘
Listening window	NA

POWER OPTIONS

Lead batteries type	**4 x 62Ah**
Lithium batteries:	**6 x 272Ah**
Fuel cells	**4 fuel cells with 10 methanol cartridges 28 litres each.**

DEPLOYMENT HISTORY

	YEAR	**MONTH**	**DATE**	**GMT**
First measurement	2016	2	12	12:00

First measurement in position	2016	2	12	12:30
Out of measuring position				
Last measurement				

Comments:	
Deployment vessel	Recovery vessel:
Deployed by:	Recovered by: